

Eurocodes

Background and Applications

Design of **Steel Buildings** with worked examples



16-17 October 2014
Brussels, Belgium

Organised and supported by

European Commission

DG Enterprise and Industry
Joint Research Centre

European Convention for Constructional Steelwork

European Committee for Standardization

CEN/TC250/SC3

Design of Structural Steel Joints

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Design of Structural Steel Joints

- Introduction
- Integration of joints into structural design process
- Moment resistant joints
- Simple joints
- Design tools

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EN 1993 Part 1.8

Chapter 1 – Introduction

Chapter 2 – Basis of design

Chapter 3 – Connections made with bolts, rivets or pins

Chapter 4 – Welded connections

Chapter 5 – Analysis, classification and modelling

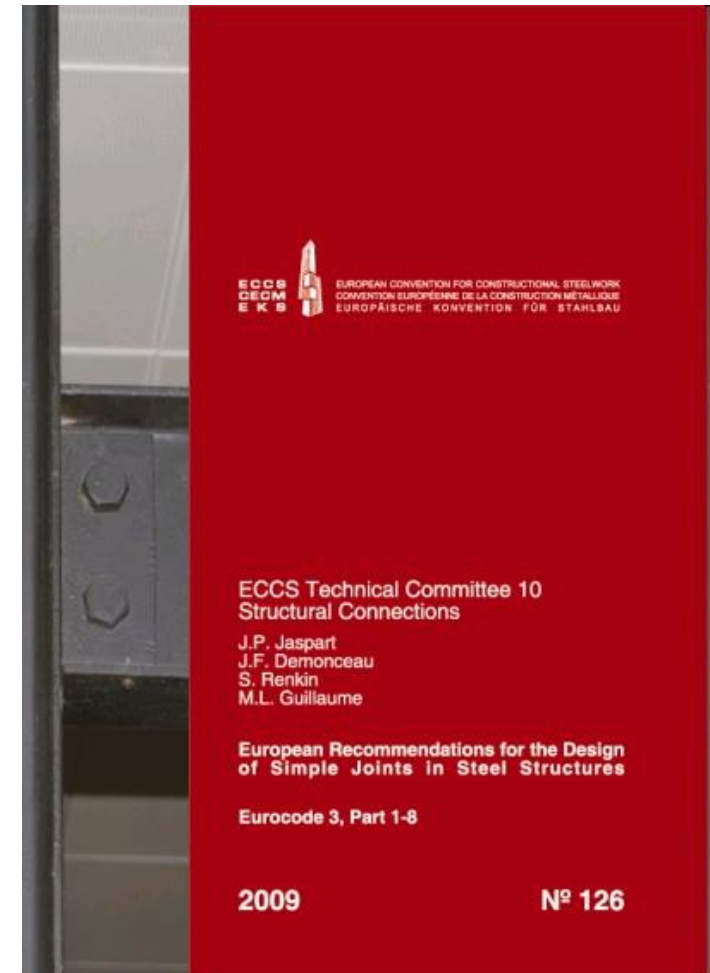
Chapter 6 – Structural joints connecting H or I sections

Chapter 7 – Hollow section joints

Design of simple joints

ECCS Publication N° 126 (EN)

- Background information
- Design guidelines



2 – Basis of design → Partial safety coefficients

Resistance of members and cross-sections	γ_{M0} , γ_{M1} and γ_{M2} see EN 1993-1-1
Resistance of bolts	γ_{M2}
Resistance of rivets	
Resistance of pins	
Resistance of welds	
Resistance of plates in bearing	
Slip resistance - at ultimate limit state (Category C) - at serviceability limit state (Category B)	γ_{M3} $\gamma_{M3,ser}$
Bearing resistance of an injection bolt	γ_{M4}
Resistance of joints in hollow section lattice girder	γ_{M5}
Resistance of pins at serviceability limit state	$\gamma_{M6,ser}$
Preload of high strength bolts	γ_{M7}
Resistance of concrete	γ_c see EN 1992

NOTE: Numerical values for γ_M may be defined in the National Annex. Recommended values are as follows: $\gamma_{M2} = 1,25$; $\gamma_{M3} = 1,25$ and $\gamma_{M3,ser} = 1,1$; $\gamma_{M4} = 1,0$; $\gamma_{M5} = 1,0$; $\gamma_{M6,ser} = 1,0$; $\gamma_{M7} = 1,1$.

3 – Connections made mechanical fasteners



4 – Welded connections



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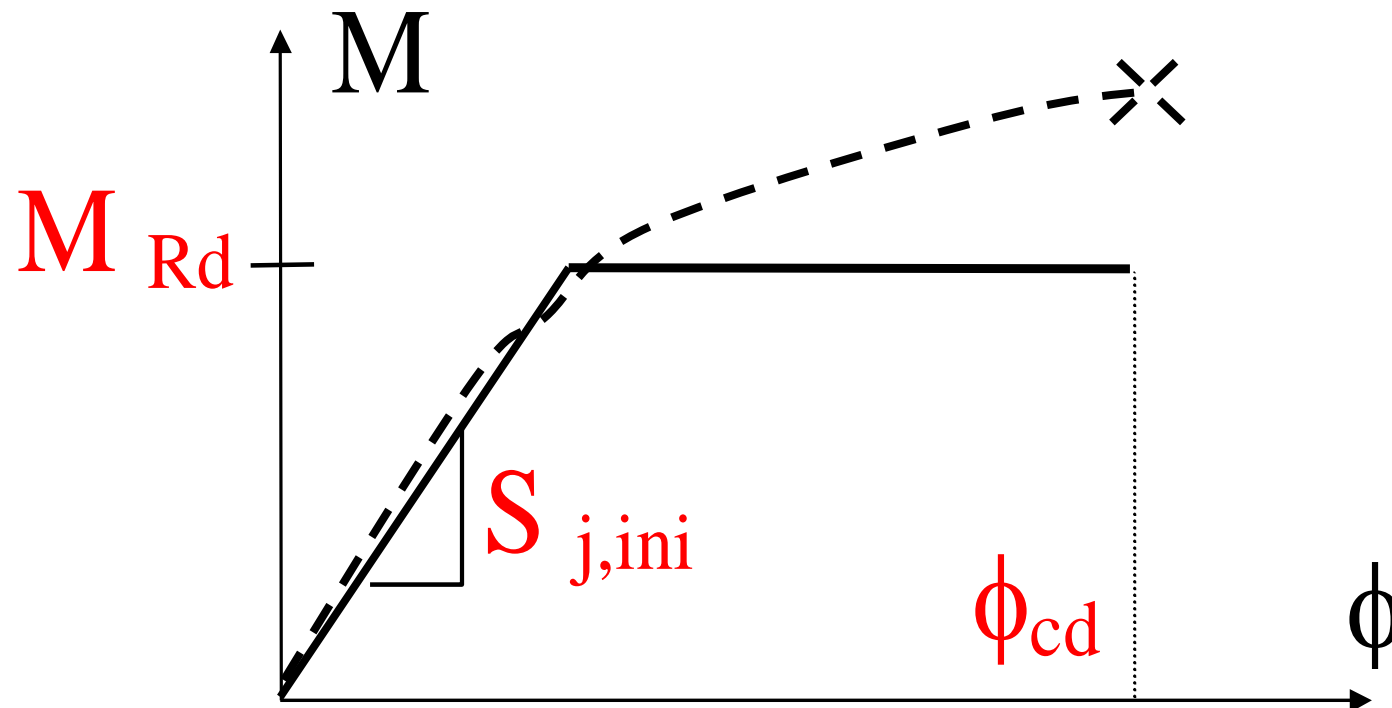
Design of Structural Steel Joints

- Introduction
- Integration of joints into structural design process
- Moment resistant joints
- Simple joints
- Design tools

Actual joint response

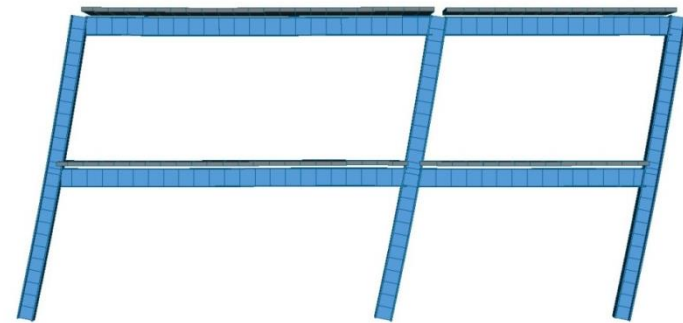
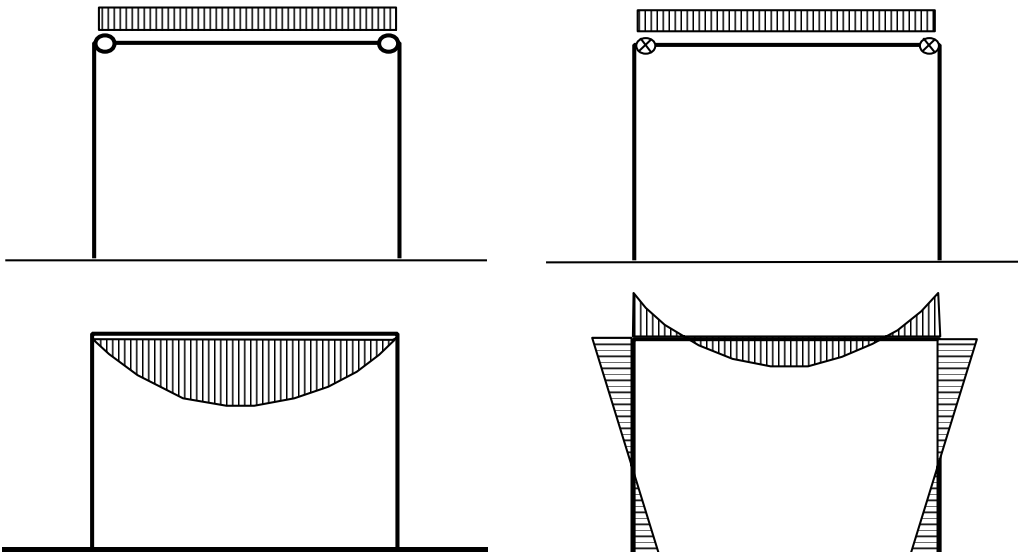


Actual joint response

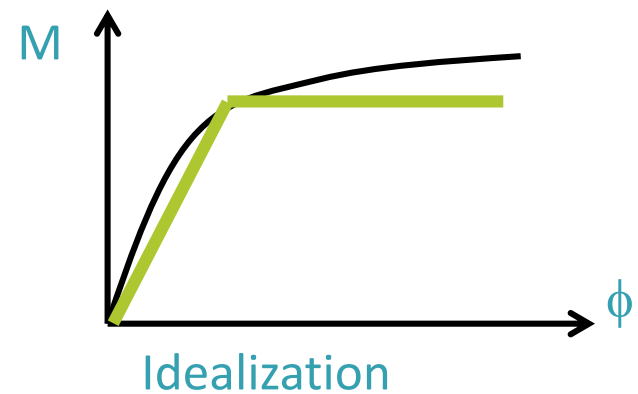
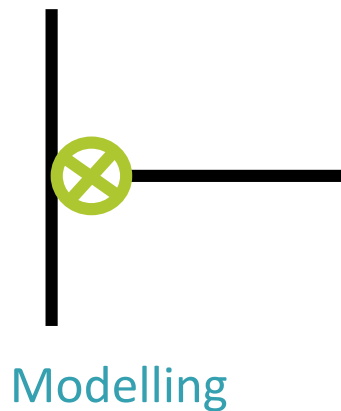
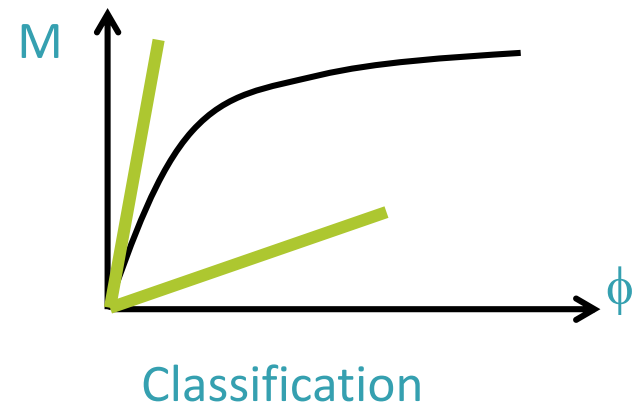
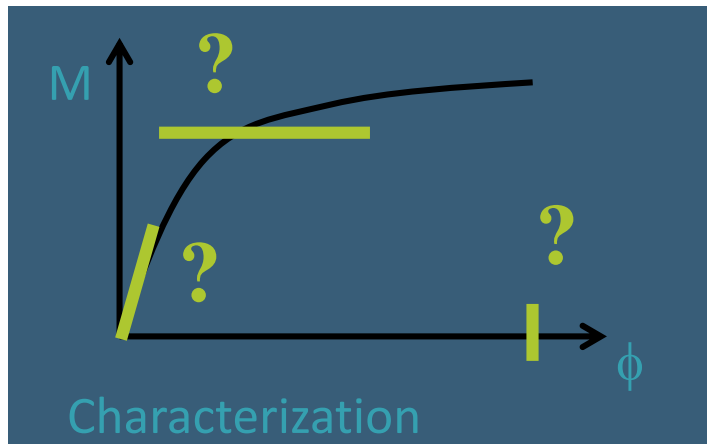


Influence on the structural response

- Displacements
- Internal forces
- Failure mode and failure load

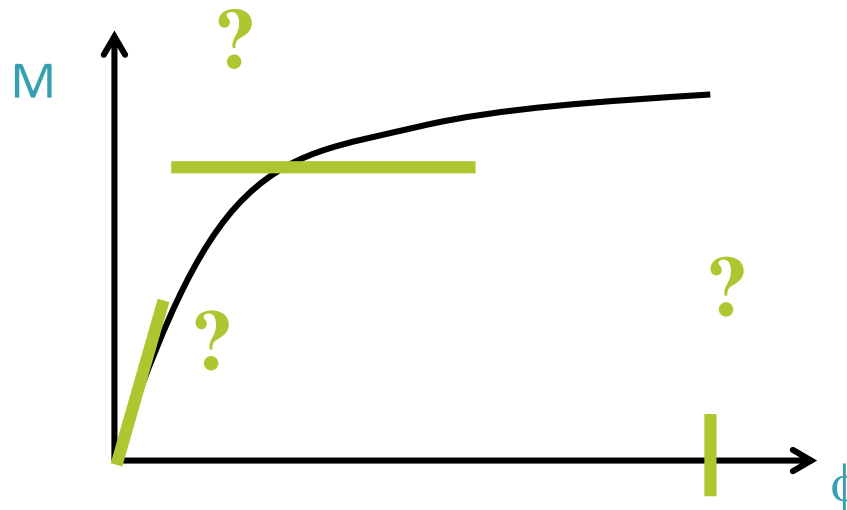


Four successive steps for structural integration



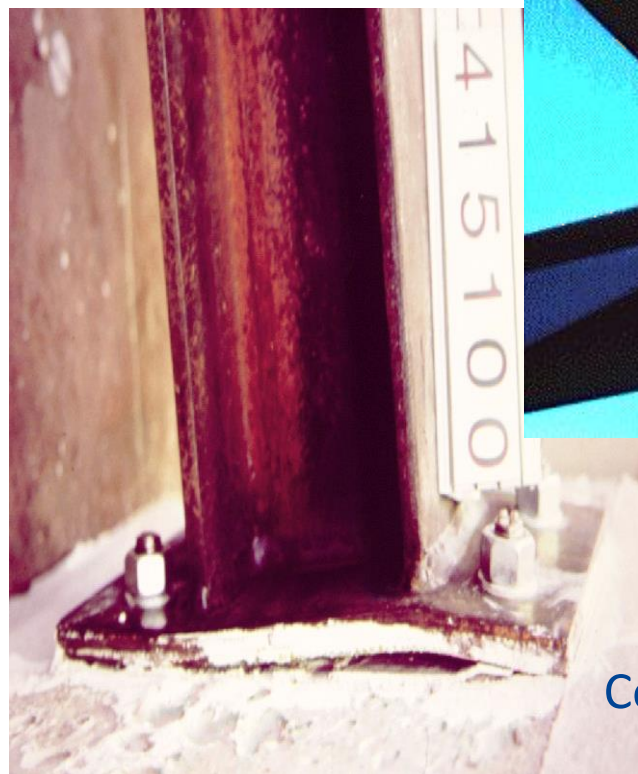
Characterization

Search for a unified approach whatever the material



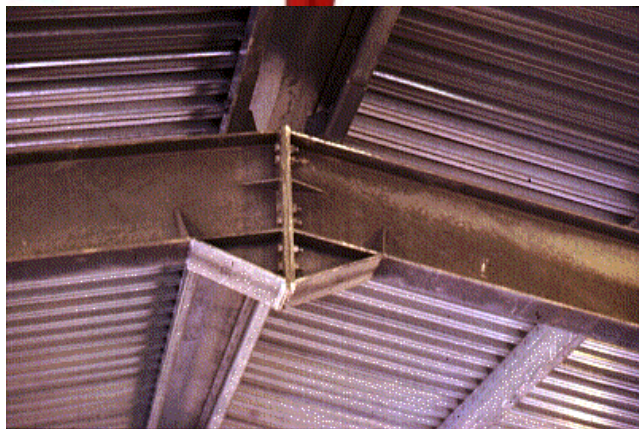
Various configurations (1)

Continuity



Various configurations (2)

Joints in portal frames



Various configurations (3)

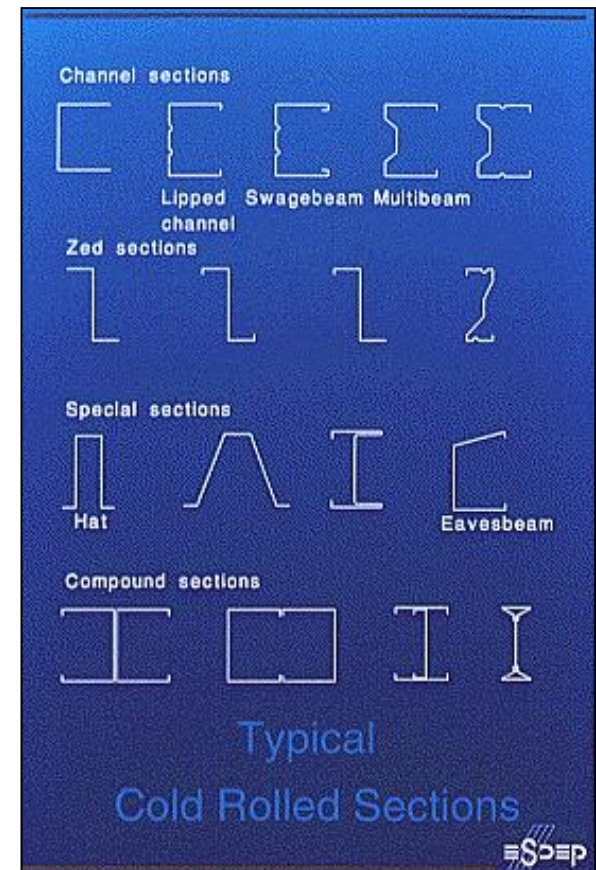
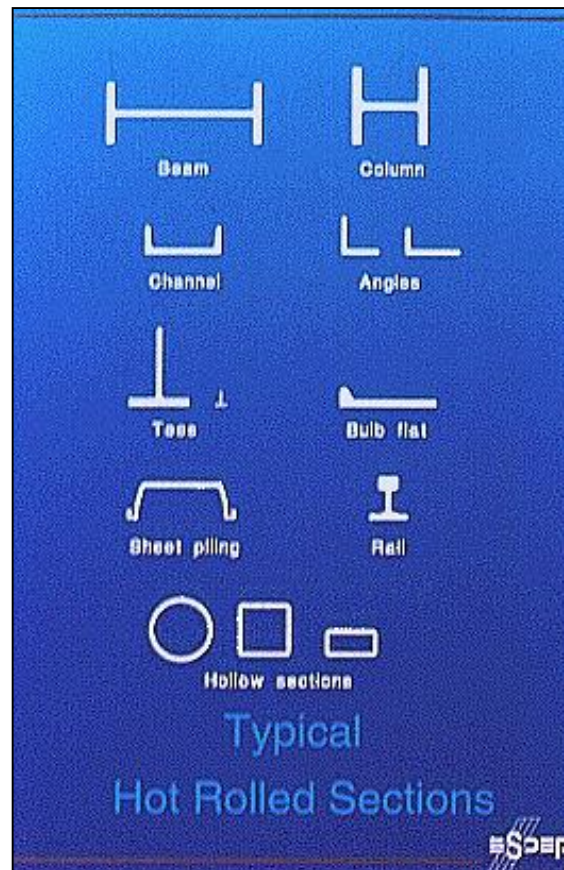


Connections and joints in
composite construction



Various cross-section shapes (1)

Hot-rolled and
cold-formed



Various cross-section shapes (2)

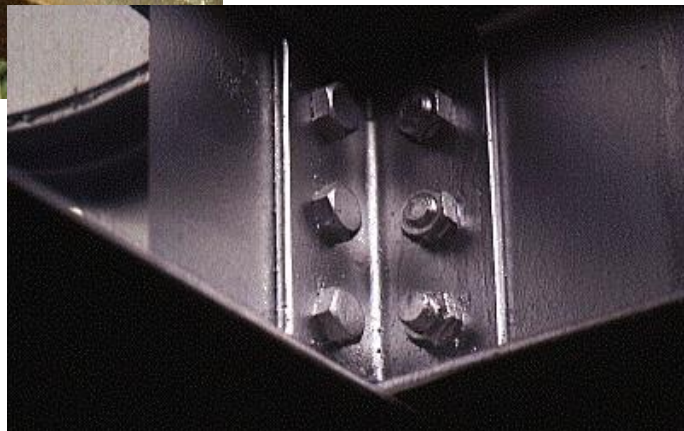
Built-up profiles



Various connection elements



End plates



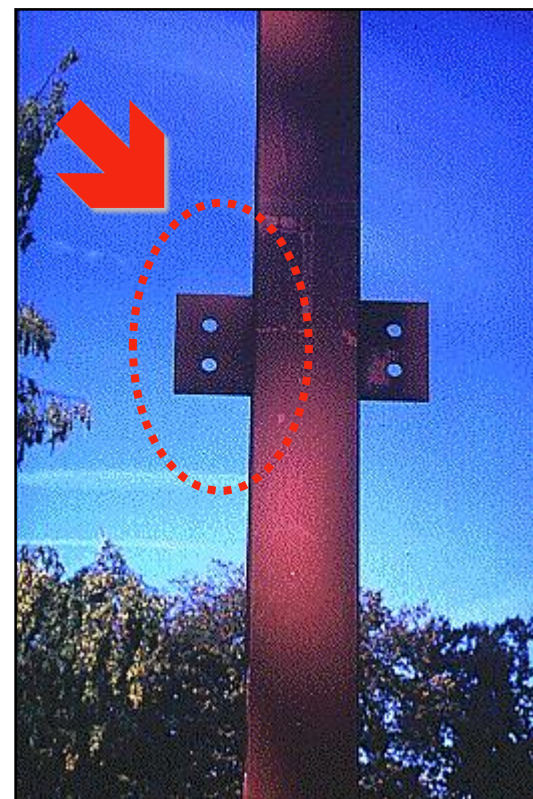
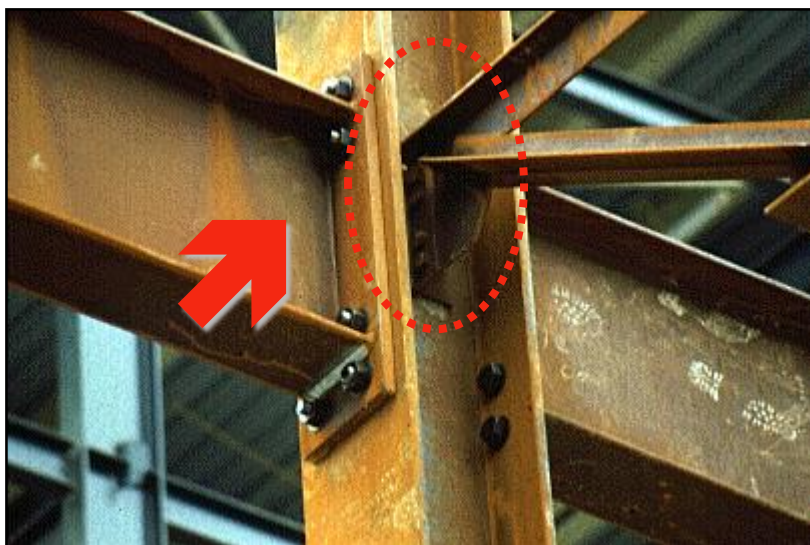
Cleats

Splices



Economy

Reduced fabrication, transportation and erection costs



Specific design criteria

Robustness

→ Joints as key elements



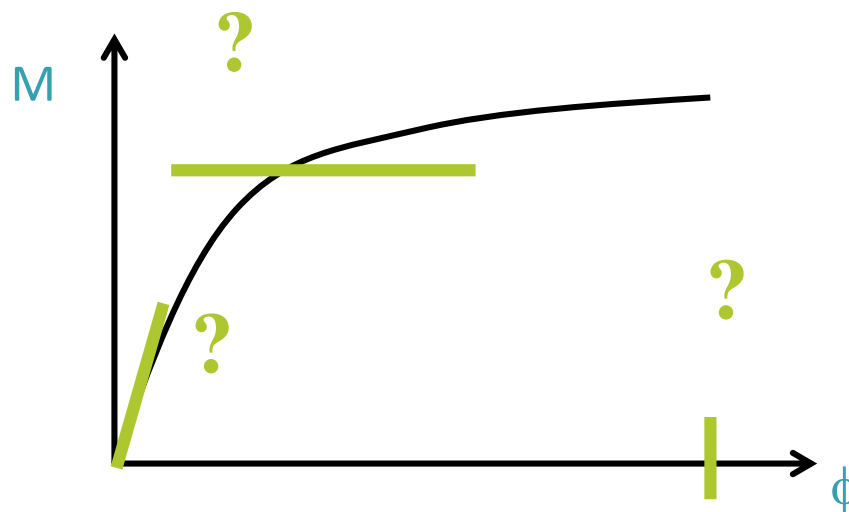
Spencer Platt / Getty Images



Shannon Stapleton / Reuters

Characterization (1)

Search for a unified approach



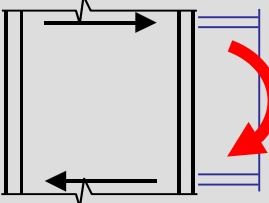
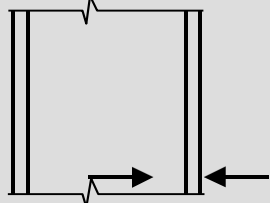
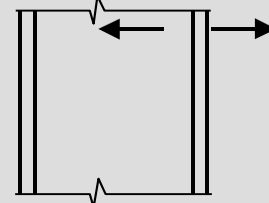
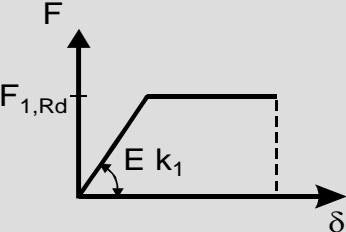
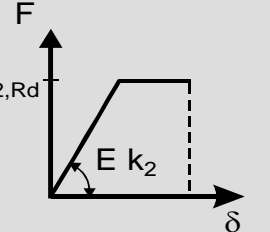
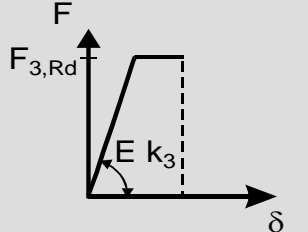
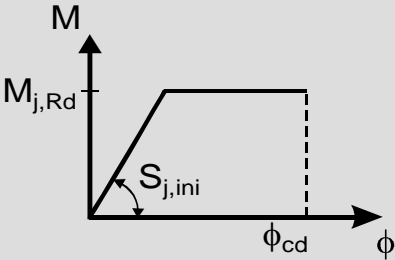
Characterization (2)

Eurocode 3 – Part 1-8

- Beam-to-beam joints, splices, beam-to-column joints and column bases:
 - welded connections
 - bolted connections (anchors for column bases)

Background: **COMPONENT METHOD**

Characterization (3) - component method

<p><u>Three steps</u></p>	<div> <div>column web in shear</div>  </div> <div> <div>column web in compression</div>  </div> <div> <div>column web in tension</div>  </div>
<p>First step</p> <p>Identification of the active components</p>	<div> <div>  </div> <div>  </div> <div>  </div> </div>
<p>Second step:</p> <p>Response of the components</p>	<div> <div>  </div> <div> $M_{j,Rd} = \min(F_{i,Rd}) \cdot z$ $S_{j,ini} = \frac{E \cdot z^2}{\sum \frac{1}{k_i}}$ </div> </div>
<p>Third step:</p> <p>“Assembly” of the components</p>	

Characterization (4) - component method

EC3 Part 1-8 provides therefore:

- a library of components
- rules for the evaluation of the properties of the components (stiffness, resistance, deformation capacity)
- rules for the evaluation of the possible component interactions
- « assembly » rules for components

Applicable for simple joint and moment resistant joint

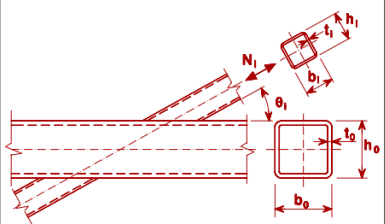
Characterization (4) – Hollow section joints

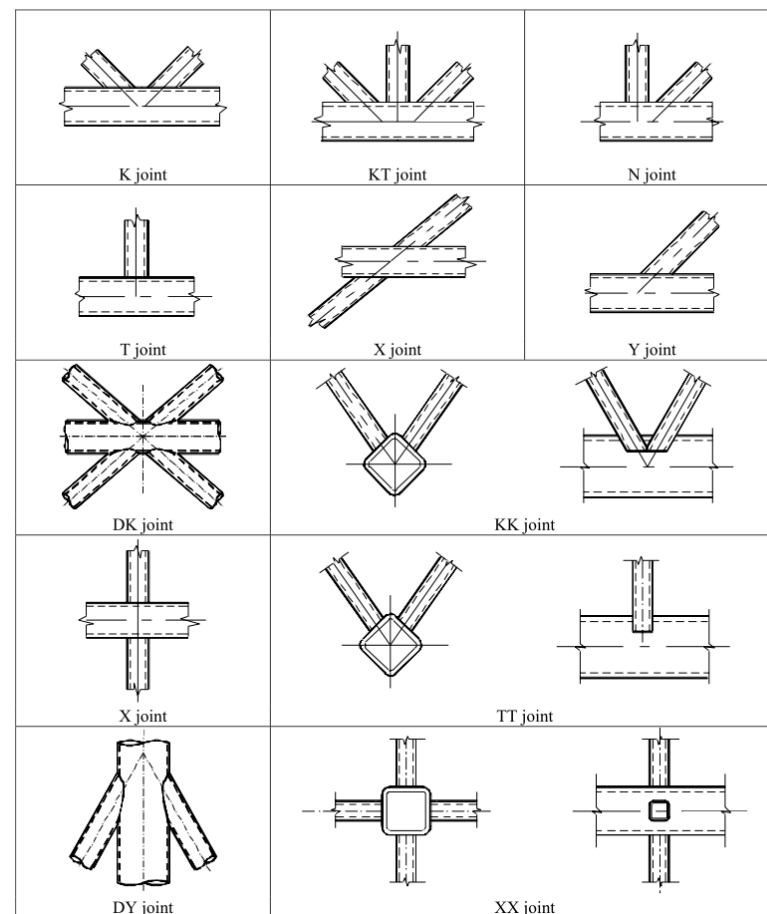
Different approach for lattice girder joints

For many types of joint configurations:

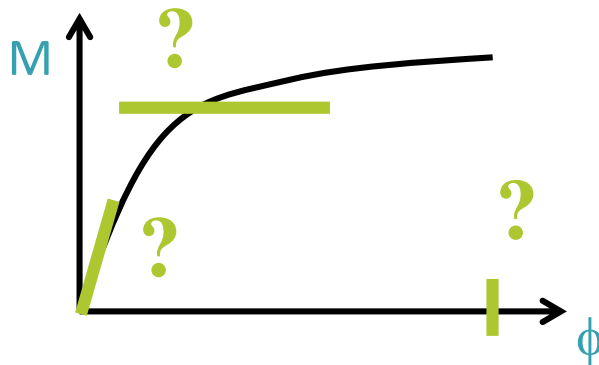
- Joints considered as a whole
- Check of relevant failure modes
- Scope of application to be checked

Table 7.11: Design axial resistances of welded T, X and Y joints between RHS or CHS braces and RHS chords

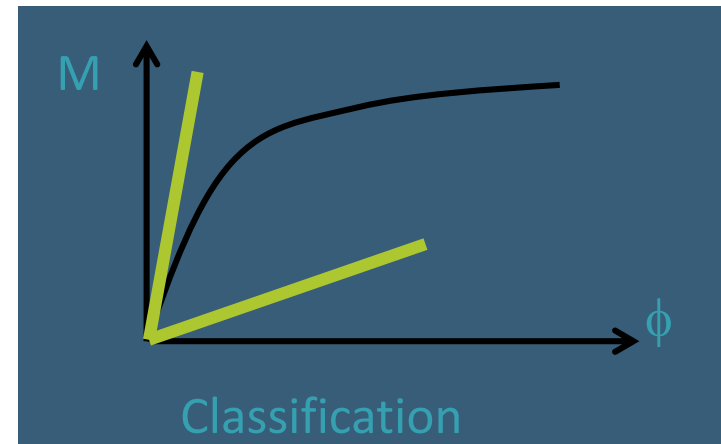
Type of joint	Design resistance [$i = 1$]
	Chord face failure $\beta \leq 0,85$
	$N_{i,Rd} = \frac{k_n f_{y0} t_o^2}{(1 - \beta) \sin \theta_i} \left(\frac{2\eta}{\sin \theta_i} + 4\sqrt{1 - \beta} \right) / \gamma_{M5}$
	Chord side wall buckling ¹⁾ $\beta = 1,0$ ²⁾
	$N_{i,Rd} = \frac{f_y t_o}{\sin \theta_i} \left(\frac{2h_i}{\sin \theta_i} + 10t_o \right) / \gamma_{M5}$
	Brace failure $\beta \geq 0,85$
	$N_{i,Rd} = f_{yt} t_i (2h_i - 4t_i + 2b_{eff}) / \gamma_{M5}$
	Punching shear $0,85 \leq \beta \leq (1 - 1/\gamma)$
	$N_{i,Rd} = \frac{f_{y0} t_o}{\sqrt{3} \sin \theta_i} \left(\frac{2h_i}{\sin \theta_i} + 2b_{e,p} \right) / \gamma_{M5}$



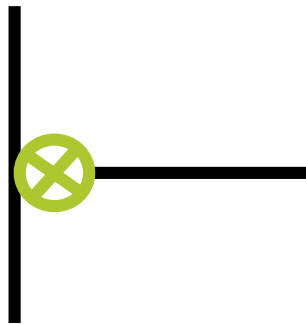
Four successive steps for structural integration



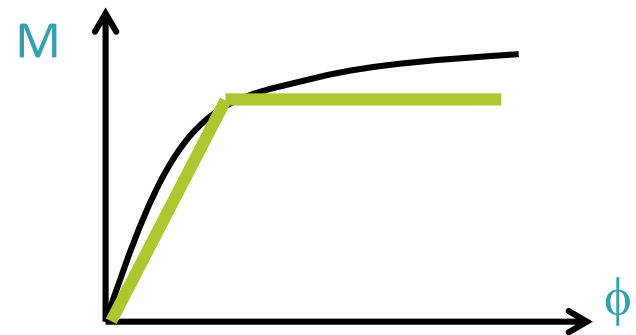
Characterization



Classification



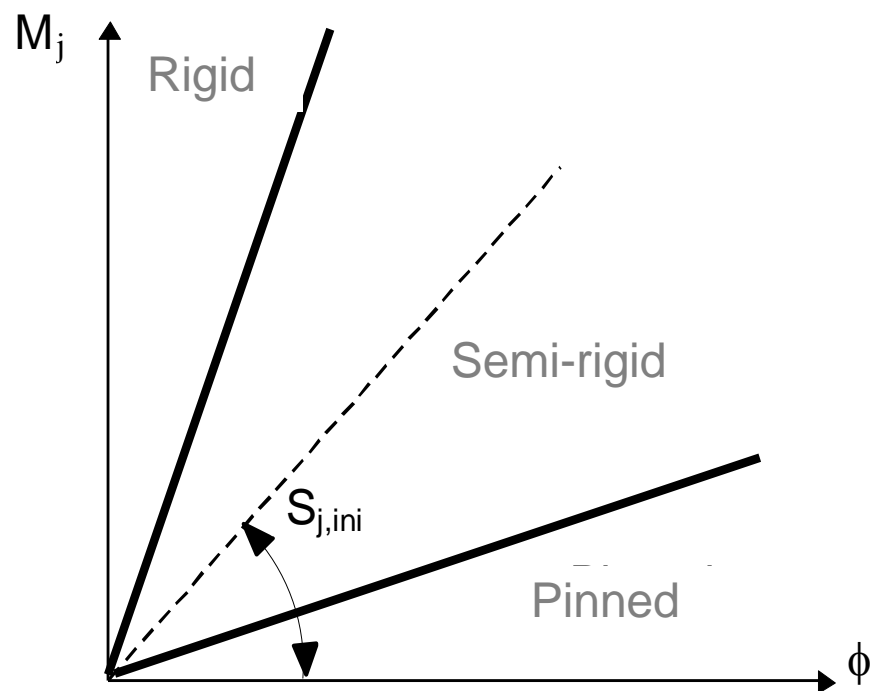
Modelling



Idealization

Classification (1)

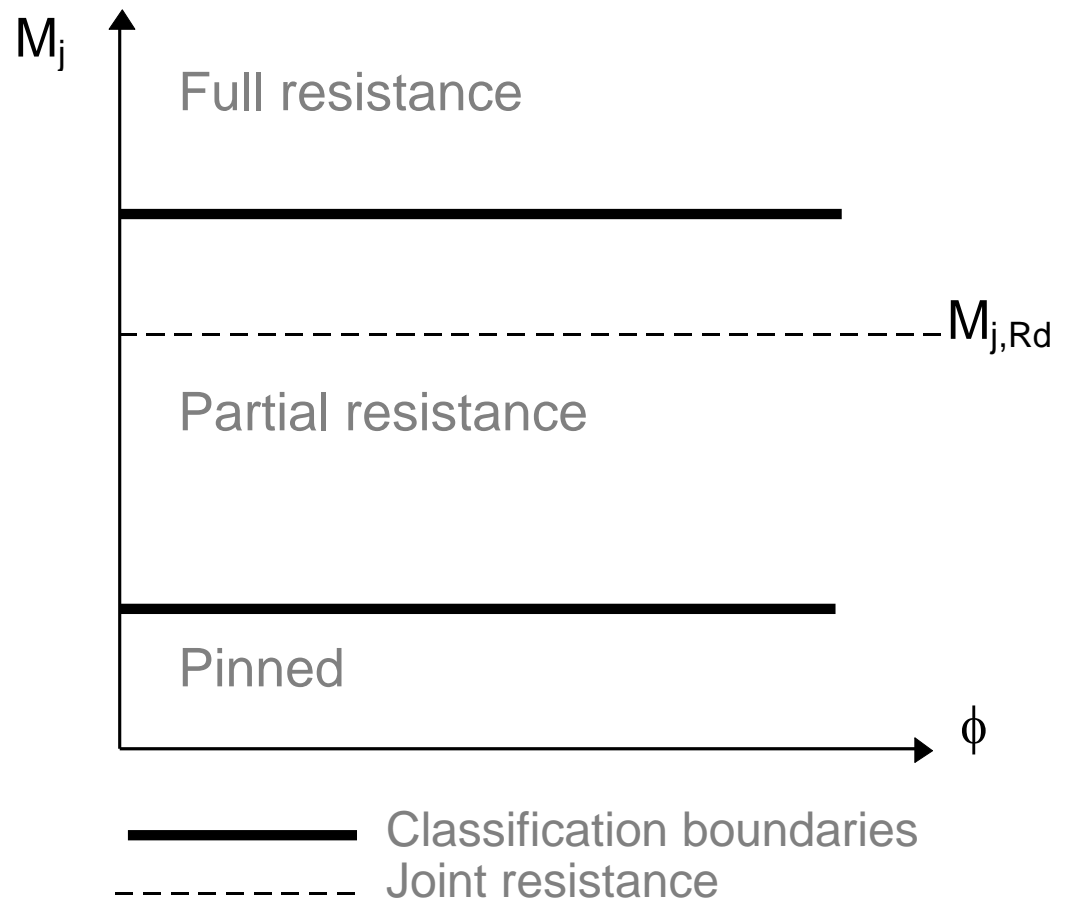
Stiffness



— Classification boundaries
- - - Initial joint stiffness

Classification (2)

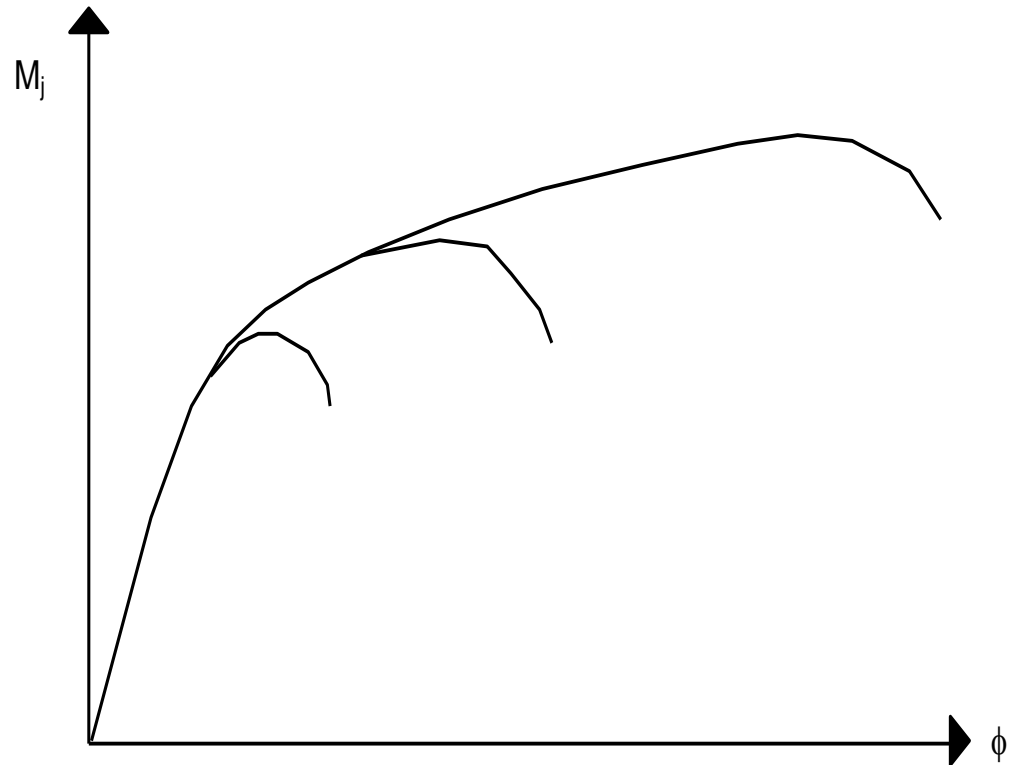
Resistance



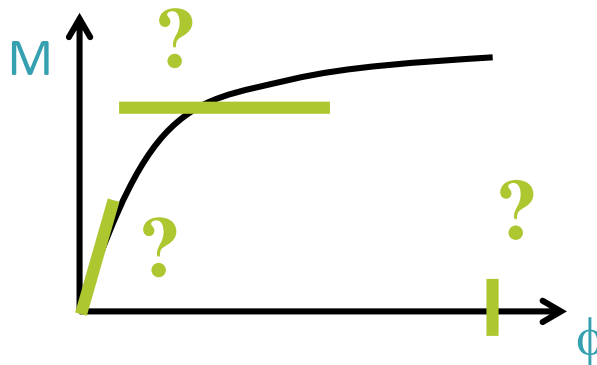
Classification (3)

Ductility

- Brittle
- "Semi-ductile"
- Ductile



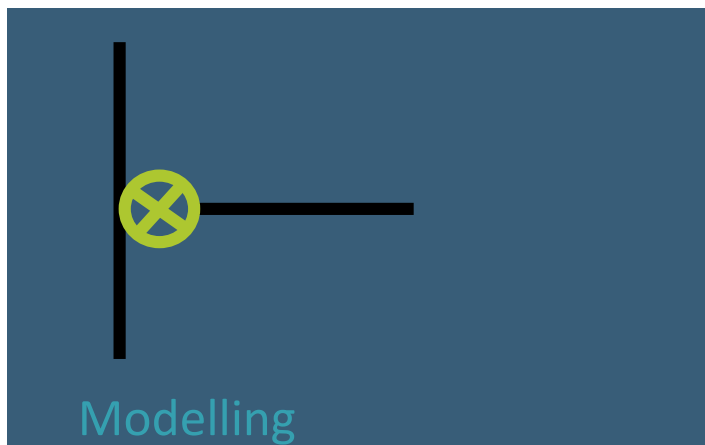
Four successive steps for structural integration



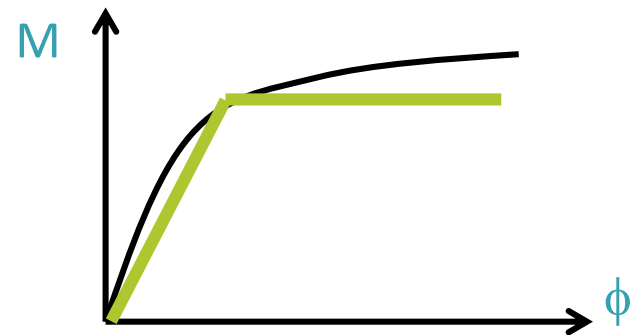
Characterization



Classification

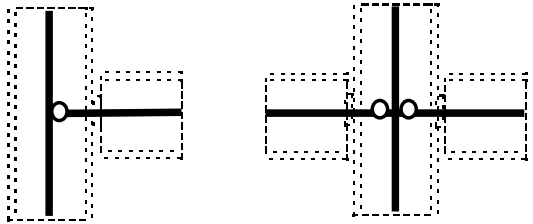
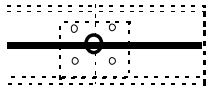
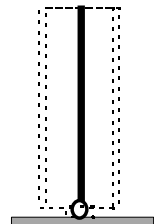
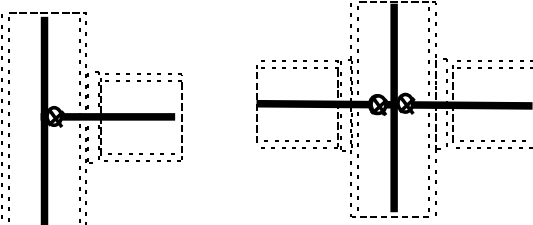

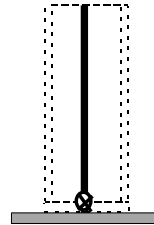
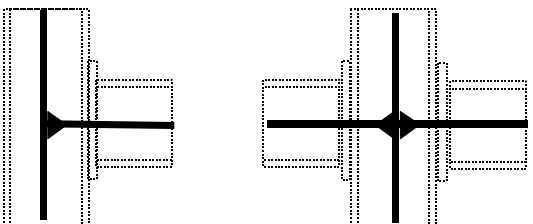
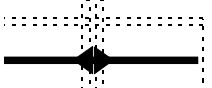
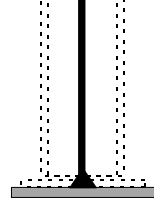


Modelling

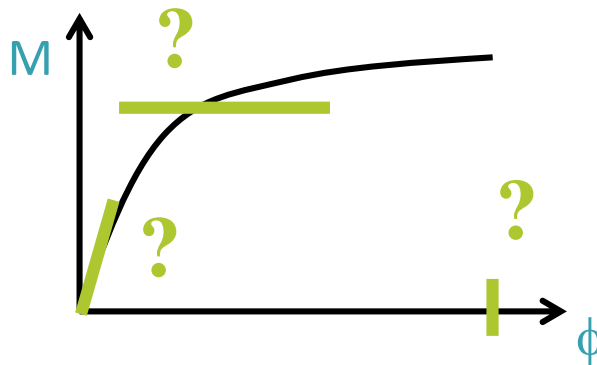


Idealization

Modelling

JOINT MODELLING	BEAM-TO-COLUMN JOINTS MAJOR AXIS BENDING	BEAM SPLICES	COLUMN BASES
SIMPLE			
SEMI-CONTINUOUS			
CONTINUOUS			

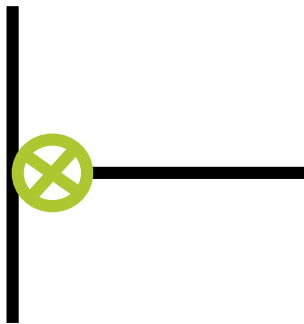
Four successive steps for structural integration



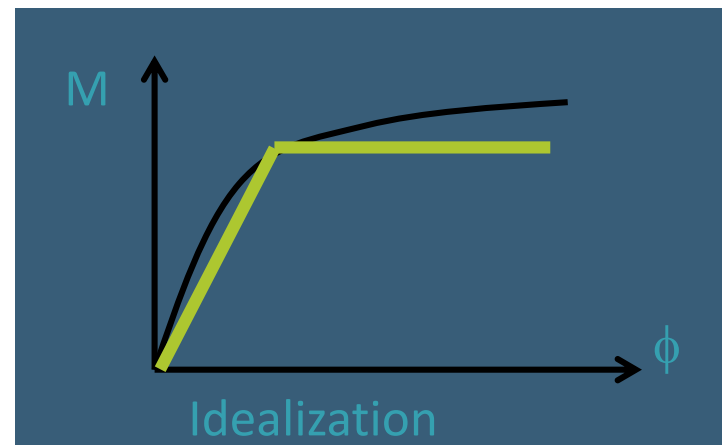
Characterization



Classification



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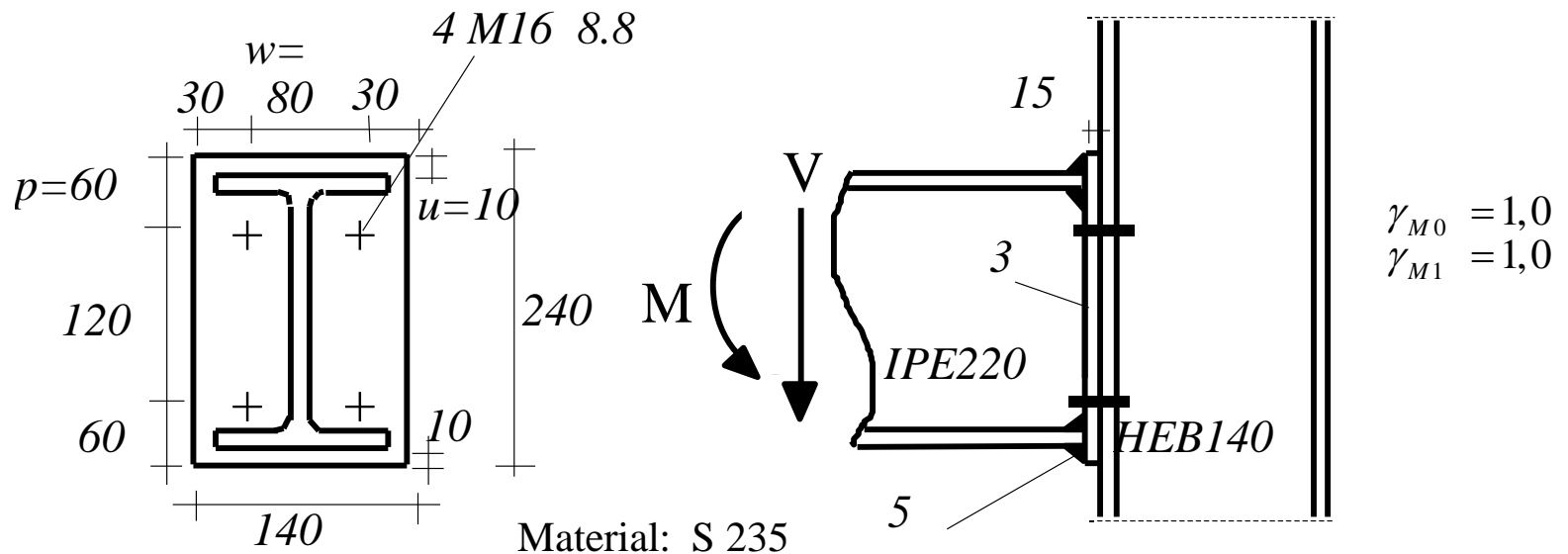
CEN/TC250/SC3

Design of Structural Steel Joints

- Introduction
- Integration of joints into structural design process
- **Moment resistant joints**
- Simple joints
- Design tools

Example

Single sided beam-to-column joint configuration, bolted end-plate connection



To be evaluated:

Design moment resistance , initial stiffness

General data

Column

$$h_{wc} = h_c - 2t_{fc} - 2r_c = 140 - 2 \times 12 - 2 \times 12 = 92 \text{ mm}$$

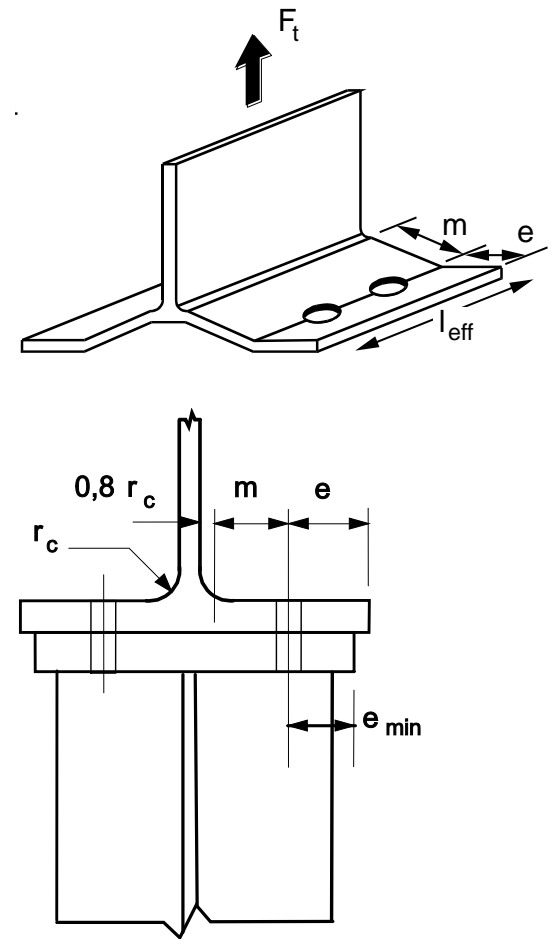
$$\begin{aligned} A_{vc} &= A_c - 2b_c t_{fc} + (t_{wc} + 2r_c) \\ &= 4295,6 - 2 \times 140 \times 12 + (7 + 2 \times 12) \times 12 = 1307,6 \text{ mm}^2 \end{aligned}$$

$$m = \frac{w - t_{fc}}{2} - 0,8 r_c = \frac{80 - 7}{2} - 0,8 \times 12 = 26,9 \text{ mm}$$

$$e = \frac{b_c - w}{2} = \frac{140 - 80}{2} = 30 \text{ mm}$$

$$m_{pl,fc} = 0,25 \frac{t_{fc}^2 f_{yc}}{\gamma_{M0}} = 0,25 \frac{12^2 \times 235}{1,0} = 8460 \text{ Nmm / mm}$$

Equivalent T-stub in tension



General data

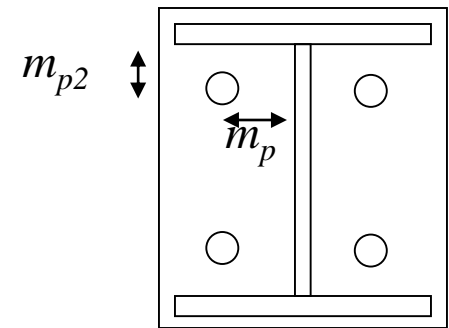
End plate

$$m_p = \frac{w - t_{wb}}{2} - 0,8\sqrt{2}a_w = \frac{80 - 5,9}{2} - 0,8 \times \sqrt{2} \times 3 = 33,66 \text{ mm}$$

$$m_{p2} = p - u - t_{fb} - 0,8\sqrt{2}a_f = 60 - 10 - 9,2 - 0,8\sqrt{2} \times 5 = 35,14 \text{ mm}$$

$$e_p = \frac{b_p - w}{2} = \frac{140 - 80}{2} = 30 \text{ mm}$$

$$m_{pl,p} = 0,25 \frac{t_p^2 f_{yp}}{\gamma_{M0}} = 0,25 \frac{15^2 \times 235}{1,0} = 13.218 \text{ Nmm / mm}$$



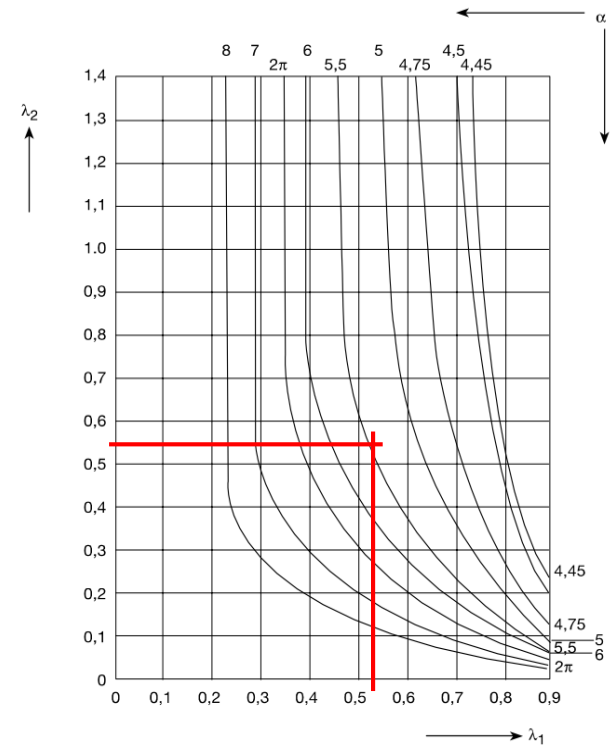
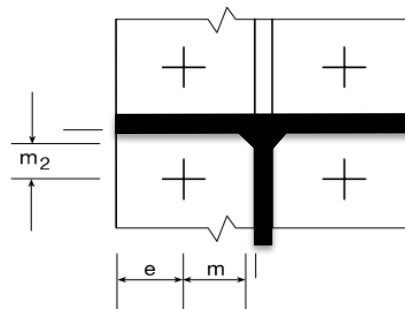
General data

End plate

Alpha factor for effective lengths

$$\lambda_1 = \frac{m_p}{m_p + e_p} = \frac{33,66}{33,66 + 30} = 0,53$$

$$\lambda_2 = \frac{m_{p2}}{m_p + e_p} = \frac{35,14}{33,66 + 30} = 0,55$$



$$\alpha = 5,5$$

General data

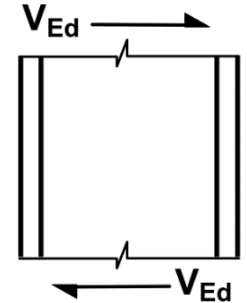
Bolts

$$F_{t,Rd} = \frac{0,9 f_{ub} A_s}{\gamma_{Mb}} = \frac{0,9 \times 800 \times 157 \times 10^{-3}}{1,25} = 90,43 kN$$

$$F_{v,Rd} \text{ (shear plane in thread)} = \frac{0,6 f_{ub} A_s}{\gamma_{Mb}} = \frac{0,6 \times 800 \times 157 \times 10^{-3}}{1,25} = 60,3 kN$$

$$L_b = t_{fc} + t_p + 0,5(h_{bolt} + h_{nut}) = 12 + 15 + \frac{1}{2}(10 + 14,8) + 2 \times 4 = 47,4 mm$$

Component N° 1 – Column web in shear



Resistance

$$V_{wc,Rd} = \frac{0,9 A_{vc} f_{y,cw}}{\sqrt{3} \gamma_{M0}} = \frac{0,9 \times 1307,6 \times 235 \times 10^{-3}}{\sqrt{3} \times 1,0} = 159,7 \text{ kN}$$

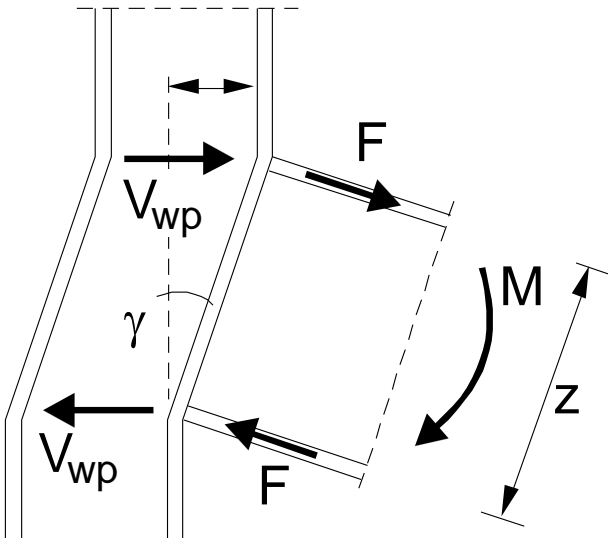
Transformation parameter

Assumption : $\beta = 1$

$$F_{Rd,1} = \frac{V_{wc,Rd}}{\beta} = \frac{159,7}{1} = 159,7 \text{ kN}$$

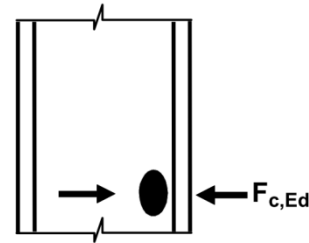
Stiffness coefficient

$$k_1 = \frac{0,38 A_{vc}}{\beta h} = \frac{0,38 \times 1307,6}{1 \times 165,4} = 3,004 \text{ mm}$$



Component N° 2 – Column web in compression

Resistance



$$\begin{aligned}
 b_{eff,c,wc} &= \min \left[t_{fb} + 2a_f \sqrt{2} + 2t_p + 5(t_{fc} + s); t_{fb} + a_f \sqrt{2} + t_p + u + 5(t_{fc} + s) \right] \\
 &= \min \left[9,2 + 2 \times 5 \times \sqrt{2} + 2 \times 15 + 5 \times (12 + 12); 9,2 + 5 \times \sqrt{2} + 15 + 10 + 5 \times (12 + 12) \right] = 161,27 \text{ mm}
 \end{aligned}$$

Reduction factors to account for compression stresses and instability

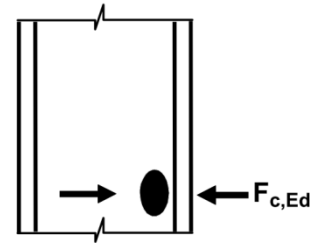
$$\text{Assumption: } k_{wc} = \min \left[1,0; 1,7 - \sigma_{com,Ed} / f_{y,wc} \right] = 1,0$$

$$\bar{\lambda}_p = 0,932 \sqrt{\frac{b_{eff,c,wc} d_c f_{y,wc}}{E t_{wc}^2}} = 0,932 \sqrt{\frac{161,27 \times 92 \times 235}{210000 \times 7 \times 7}} = 0,543 \leq 0,673 \rightarrow \rho = 1,0$$

$$\omega = \omega_1 = \sqrt{\frac{1}{1 + 1,3 \left(b_{eff,c,wc} t_{wc} / A_{vc} \right)^2}} = \sqrt{\frac{1}{1 + 1,3 (161,27 \times 7 / 1307,6)^2}} = 0,713$$

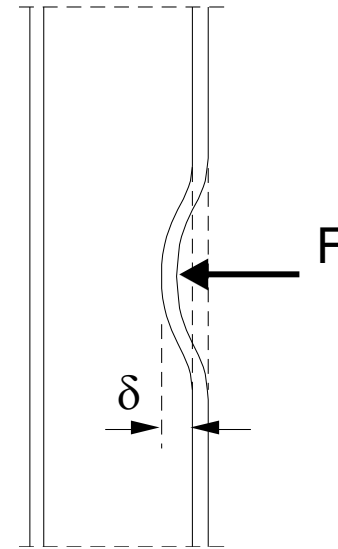
$$F_{Rd,2} = k_{wc} \omega \rho b_{eff,c,wc} t_{wc} f_{y,wc} / \gamma_{M1} = 1 \times 0,713 \times 1 \times 161,27 \times 7 \times 235 \times 10^{-3} / 1,0 = 189,1 \text{ kN}$$

Component N° 2 – Column web in compression



Stiffness coefficient

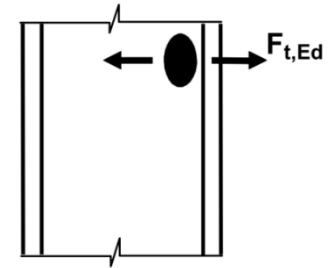
$$k_2 = \frac{0,7 b_{eff,c,wc} t_{wc}}{h_{wc}} = \frac{0,7 \times 161,27 \times 7}{92} = 8,589 mm$$



$$F_i = k_i E \delta_i$$

Component N° 3 – Column web in tension

Resistance



$$b_{eff,t,wc} = \min[2\pi m; 4m + 1,25e] = \min(2\pi \times 26,9; 4 \times 26,9 + 1,25 \times 30) = 145,10 \text{ mm}$$

$$\omega_1 = \sqrt{\frac{1}{1 + 1,3(b_{eff,t,wc} t_{wc} / A_{vc})^2}} = \sqrt{\frac{1}{1 + 1,3(145,1 \times 7 / 1307,6)^2}} = 0,749$$

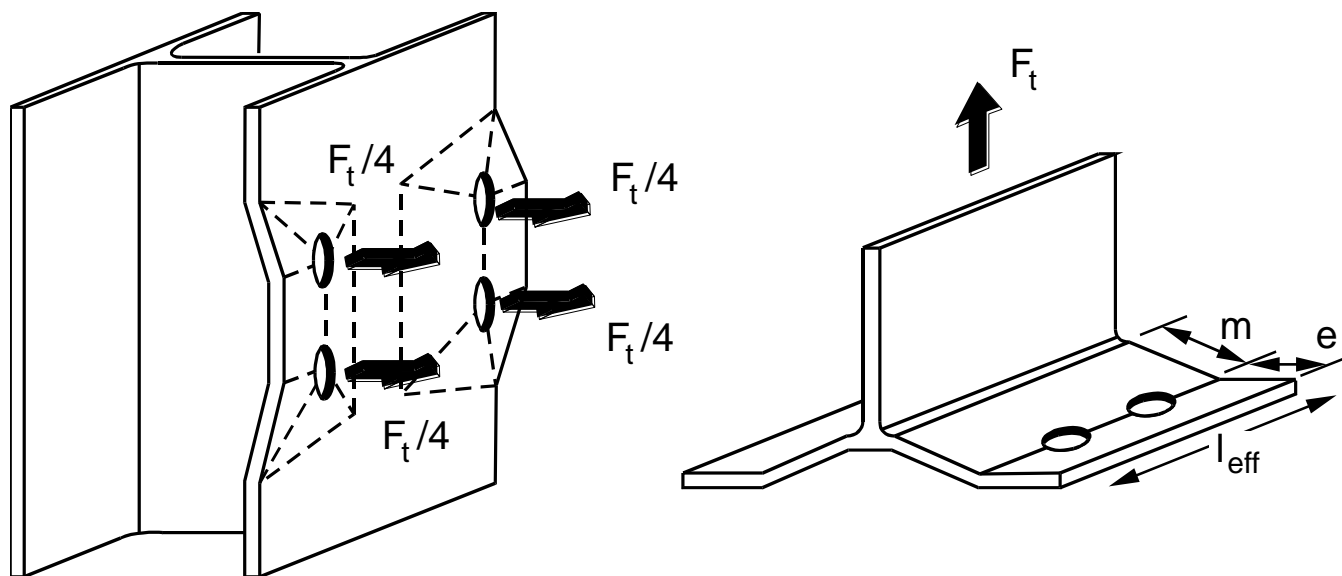
$$F_{Rd,3} = \omega b_{eff,t,wc} t_{wc} f_{y,wc} / \gamma_{M0} = 0,749 \times 145,1 \times 7 \times 235 \times 10^{-3} / 1,0 = 178,7 \text{ kN}$$

Stiffness coefficient

$$k_3 = \frac{0,7 b_{eff,t,wc} t_{wc}}{h_{wc}} = \frac{0,7 \times 145,1 \times 7}{92} = 7,728 \text{ mm}$$

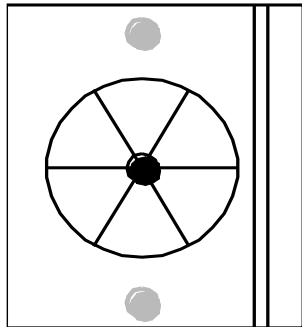
Component N° 4 – Column flange in bending Component N° 5 – End plate in bending

Equivalent T-stub in tension

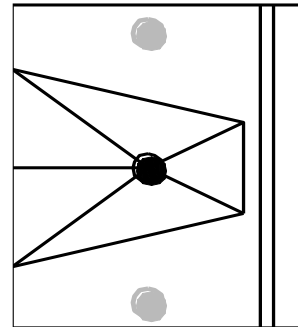


T-stub – Effective length

Distinction between circular and non-circular yield line patterns



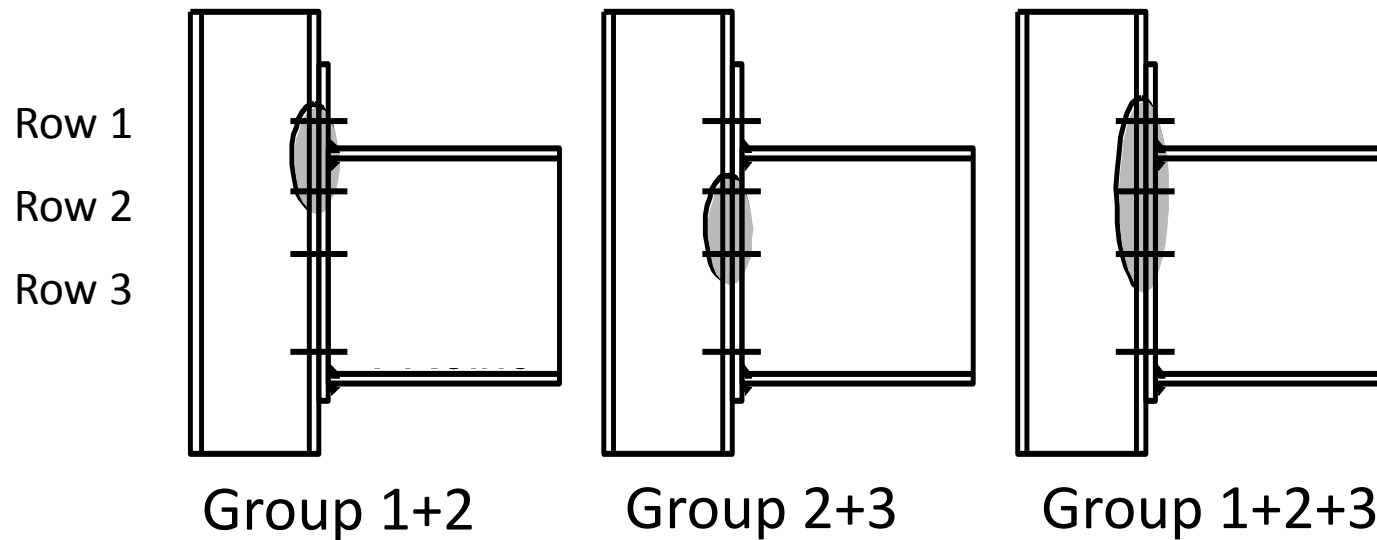
Circular patterns



Non-circular patterns

T-stub – Effective length

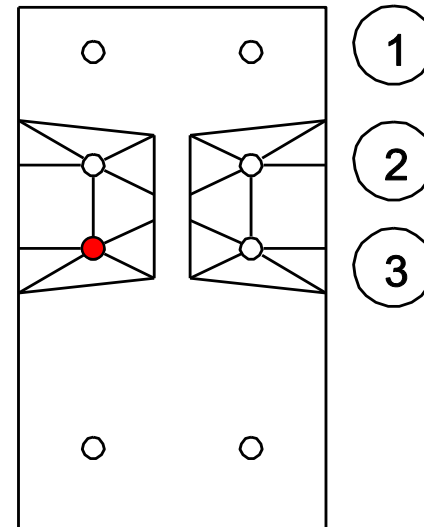
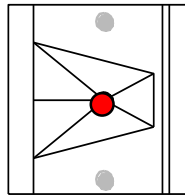
Groups effects to consider in addition to the individual response of each bolt-row



T-stub – Effective length

Groups effects to consider in addition to the individual response of each bolt-row

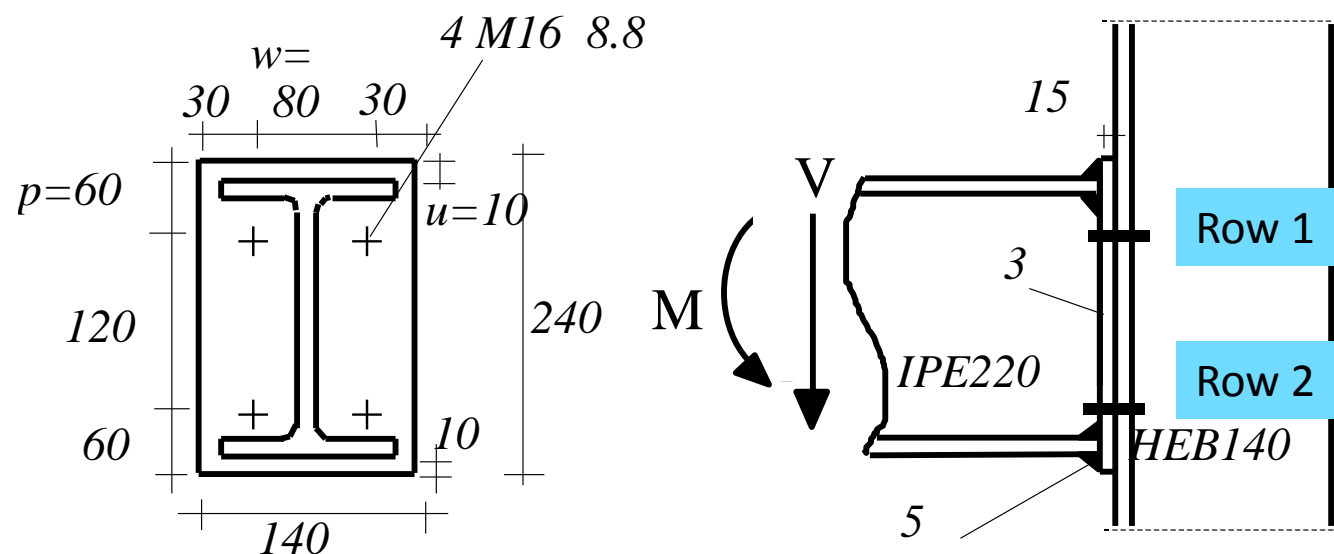
Row 3



$$F_{Rd,3} = \min (F_{Rd,3,indiv}; F_{Rd,3,group})$$

Bolt rows considered

In this example: only bolt row 1 is considered for tension forces

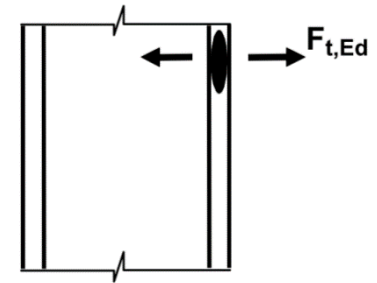


Component N° 4 – Column flange in bending

Resistance

$$l_{eff,t,fc} = b_{eff,t,wc} = 145,1mm \quad (\text{see column web in tension})$$

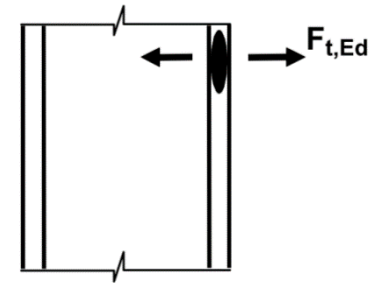
$$n = \min \left[e; 1,25m; (b_p - w) / 2 \right] = \min (30; 1,25 \times 26,9; 30) = 30mm$$



Component N° 4 – Column flange in bending

Mode 1 - Complete yielding of the flange

$$F_{fc,Rd,t1} = \frac{4l_{eff,t,fc} m_{pl,fc}}{m} = \frac{4 \times 145,1 \times 8460}{26,9} \times 10^{-3} = 182,5 kN$$



Mode 2 - Bolt failure with yielding of the flange

$$F_{fc,Rd,t2} = \frac{2l_{eff,t,fc} m_{pl,fc} + 2B_{t,Rd} n}{m + n} = \frac{2 \times 145,1 \times 8460 + 2 \times 90,4 \times 10^3 \times 30}{26,9 + 30} \times 10^{-3} = 138,5 kN$$

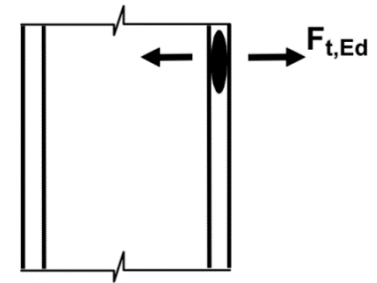
Mode 3 - Bolt failure

$$F_{fc,Rd,t3} = 2B_{t,Rd} = 2 \times 90,43 = 180,9 kN$$

Component N° 4 – Column flange in bending

Resistance

$$F_{Rd,4} = \min \left[F_{fc,Rd,t1}; F_{fc,Rd,t2}; F_{fc,Rd,t3} \right] = 138,5 kN$$



Stiffness coefficient

$$k_4 = \frac{0,9 l_{eff,fc,t} t_{fc}^3}{m^3} = \frac{0,9 \times 145,1 \times 12^3}{26,9^3} = 11,59 mm$$

Component N° 5 – End plate in bending

Resistance

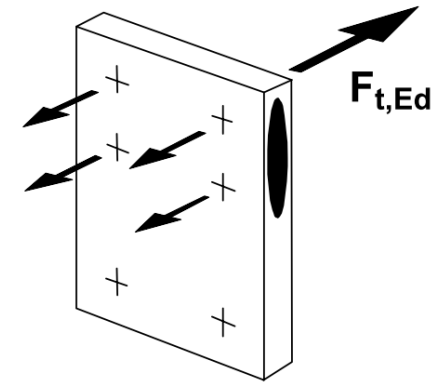
$$l_{eff,t,p} = \min \left[2\pi m_p ; \alpha m_p \right] = \min (2\pi \times 33,66 ; 5,5 \times 33,66) = 185 \text{ mm}$$

$$n_p = \min \left[e_p ; 1,25m_p ; e \right] = \min (30 ; 1,25 \times 33,66 ; 30) = 30 \text{ mm}$$

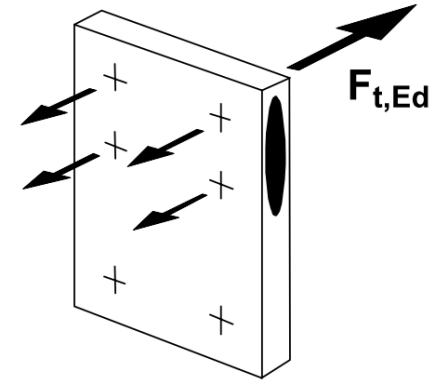
$$\text{Mode 1: } F_{ep,Rd,1} = \frac{4l_{eff,t,p} m_{pl,p}}{m_p} = \frac{4 \times 185 \times 13.218}{33,66} \times 10^{-3} = 291 \text{ kN}$$

$$\text{Mode 2: } F_{ep,Rd,2} = \frac{2l_{eff,p,t} m_{pl,p} + 2B_{t,Rd} n_p}{m_p + n_p} = \frac{2 \times 185 \times 13.218 + 2 \times 90,43 \times 10^3 \times 30}{33,66 + 30} \times 10^{-3} = 162,1 \text{ kN}$$

$$F_{Rd,5} = \min \left[F_{ep,Rd,1} ; F_{ep,Rd,2} ; F_{ep,Rd,3} \right] = 162,1 \text{ kN}$$



Component N° 5 – End plate in bending



Stiffness coefficient

$$k_5 = \frac{0,9 l_{eff,t,p} t_p^3}{m_p^3} = \frac{0,9 \times 185,0 \times 15^3}{33,66^3} = 14,73 mm$$

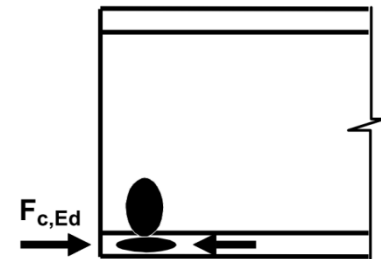
Component N° 7 – Beam flange and web in compression

Resistance

$$F_{Rd,7} = M_{c,Rd} / (h_b - t_{fb}) = \frac{67,07}{210,8 \times 10^{-3}} = 318,2 \text{ kN}$$

Stiffness coefficient

$$k_7 = \infty$$

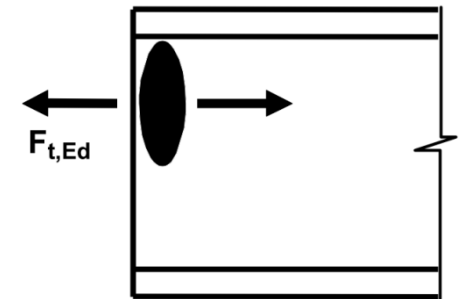


Component N° 8 – Beam web in tension

Resistance

$$b_{eff,t,wb} = l_{eff,t,p} = 185mm$$

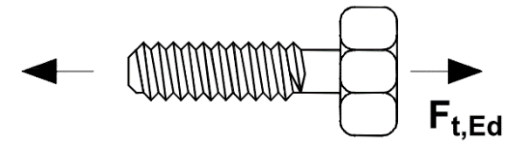
$$F_{Rd,8} = b_{eff,t,wb} t_{wb} f_{yb} / \gamma_{M0} = 185 \times 5,9 \times 235 \times 10^{-3} / 1,0 = 256,5kN$$



Stiffness coefficient

$$k_8 = \infty$$

Component N° 10 – Bolts in tension



Resistance

$$F_{Rd,10} = 2B_{t,Rd} = 2 \times 90,43 = 180,9 \text{ kN} \quad \rightarrow \text{Mode 3 in T-stubs for components:}$$

- “column flange in bending”
- “end plate in bending”

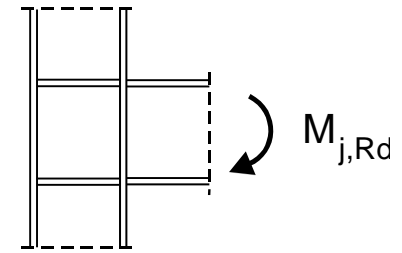
Stiffness coefficient

$$k_{10} = 1,6 \frac{A_s}{L_b} = 1,6 \times \frac{157}{47,4} = 5,30 \text{ mm}$$

Design moment resistance

Relevant component

$$F_{Rd} = \min[F_{Rd,i}] = 138,5 \text{ kN} \quad (\text{Column flange in bending})$$



Design plastic moment resistance

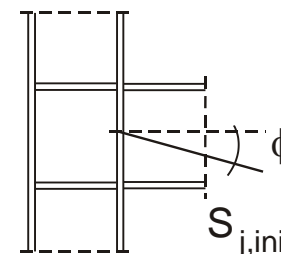
$$M_{j,Rd} = F_{Rd} z = 138,5 \times 165,4 \times 10^{-3} = 22,91 \text{ kNm}$$

Design elastic moment resistance

$$M_{j,el,Rd} = \frac{2}{3} M_{j,Rd} = 15,27 \text{ kNm}$$

Stiffness

Initial stiffness

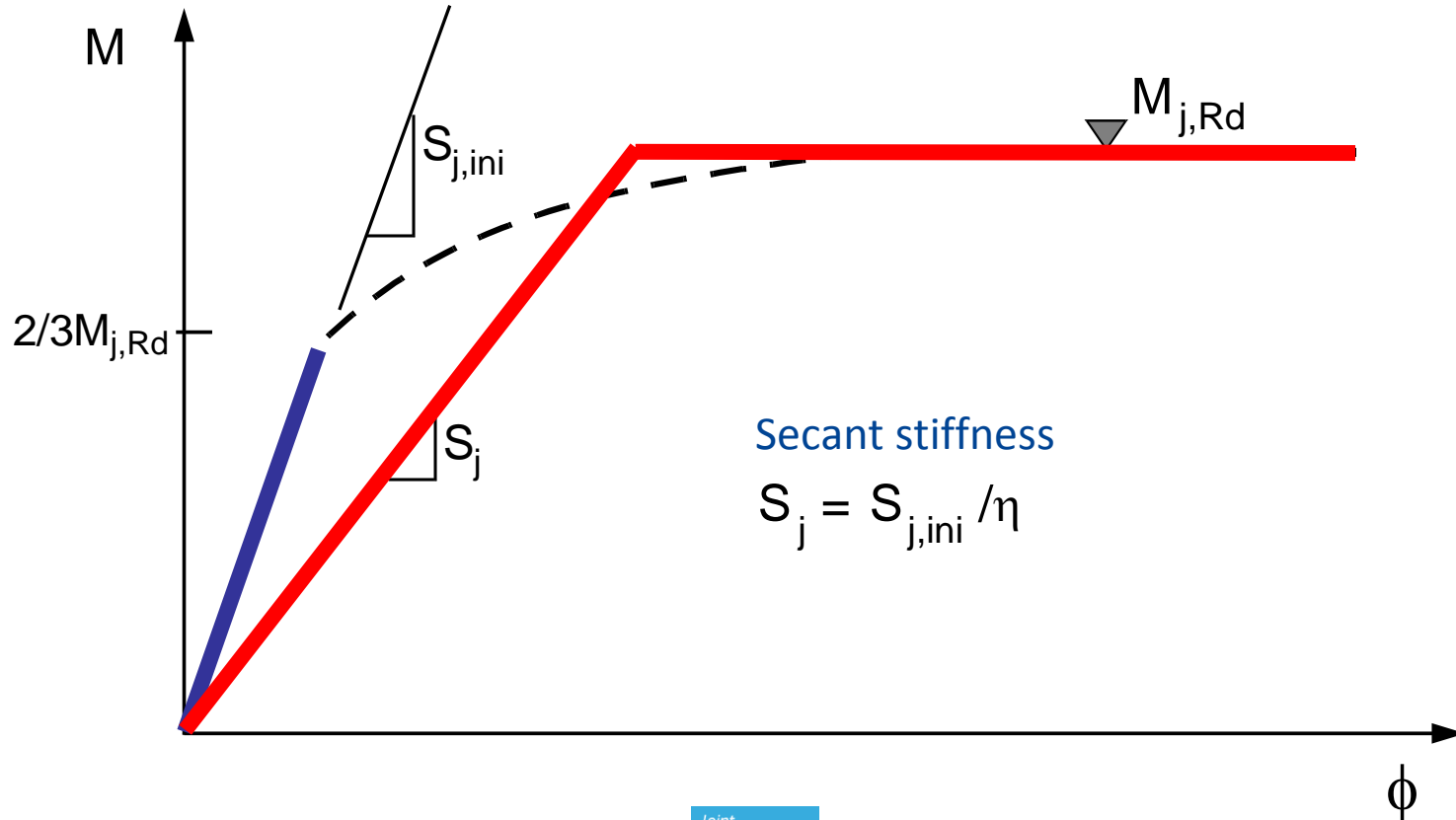


$$S_{j,ini} = E h^2 / \sum_i 1/k_i = \frac{210000 \times 165,4^2 \times 10^{-6}}{\frac{1}{3,004} + \frac{1}{8,589} + \frac{1}{7,728} + \frac{1}{11,59} + \frac{1}{14,73} + \frac{1}{5,30}} = 6234 \text{ kNm / rad}$$

Secant stiffness

$$S_j = S_{j,ini} / 2 = 3117 \text{ kNm / rad}$$

Design moment-rotation characteristic



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Background and Applications

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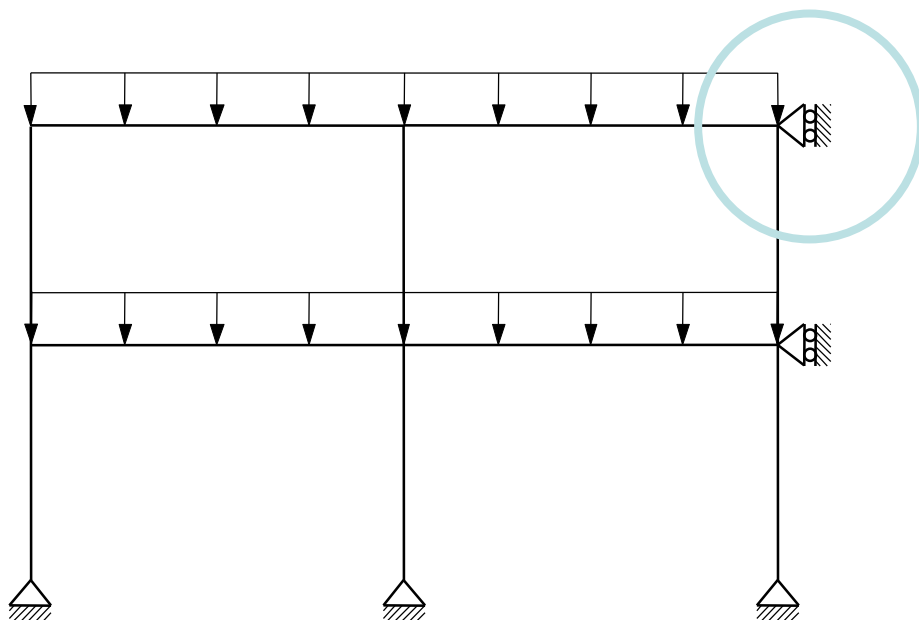
European Committee for Standardization

CEN/TC250/SC3

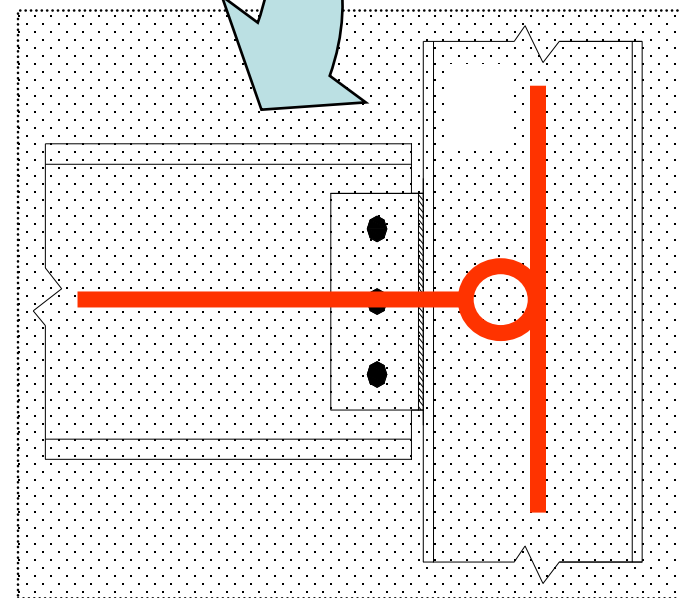
Design of Structural Steel Joints

- Introduction
- Integration of joints into structural design process
- Moment resistant joints
- **Simple joints**
- Design tools

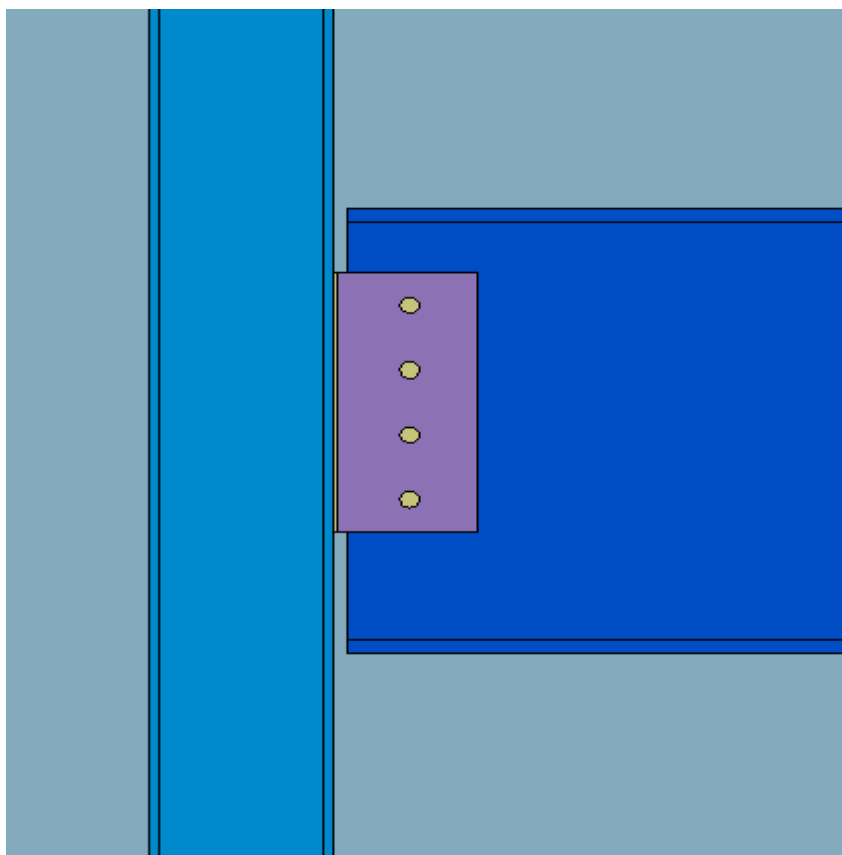
Nominally pinned joints

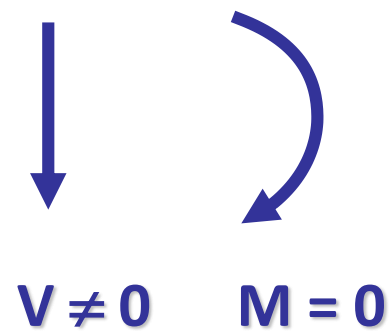


Braced frame



Nominally pinned joints



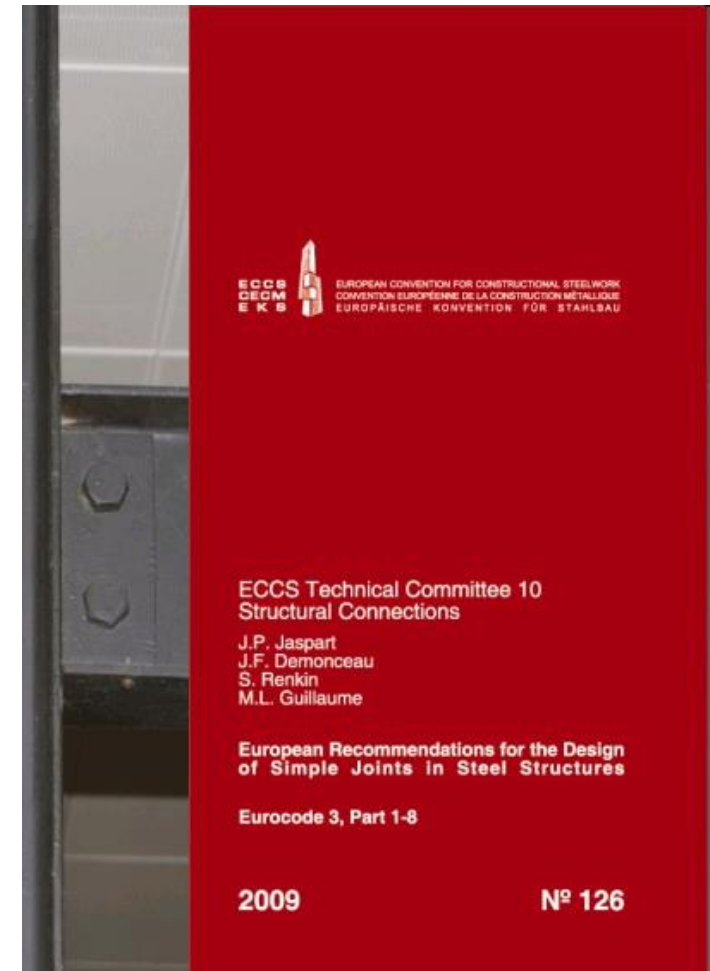


$V \neq 0$ $M = 0$

Design of simple joints

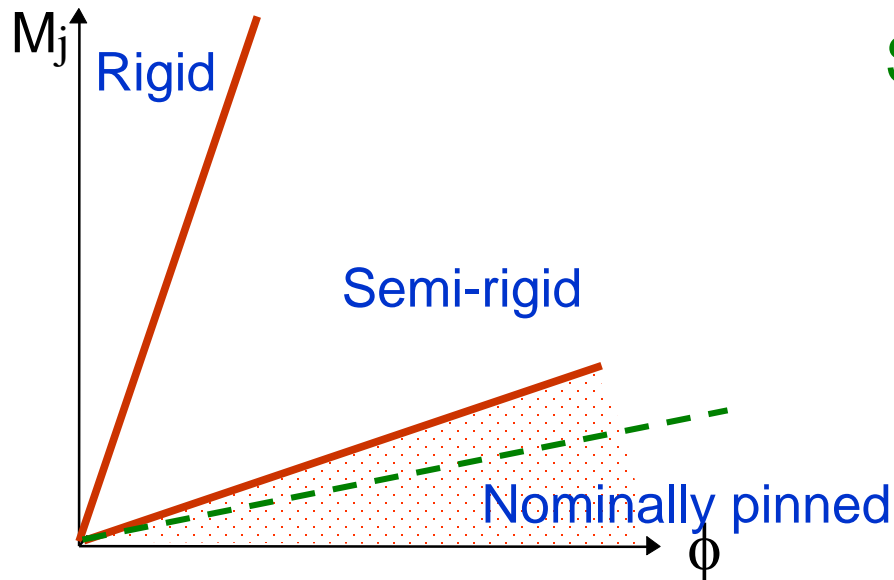
ECCS Publication N° 126 (EN)

- Background information
- Design guidelines

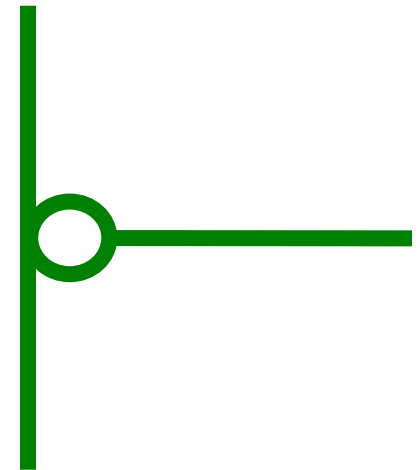


Classification and modelling of joints

“Nominally pinned” joints :



$$S_{j,ini} \ll$$

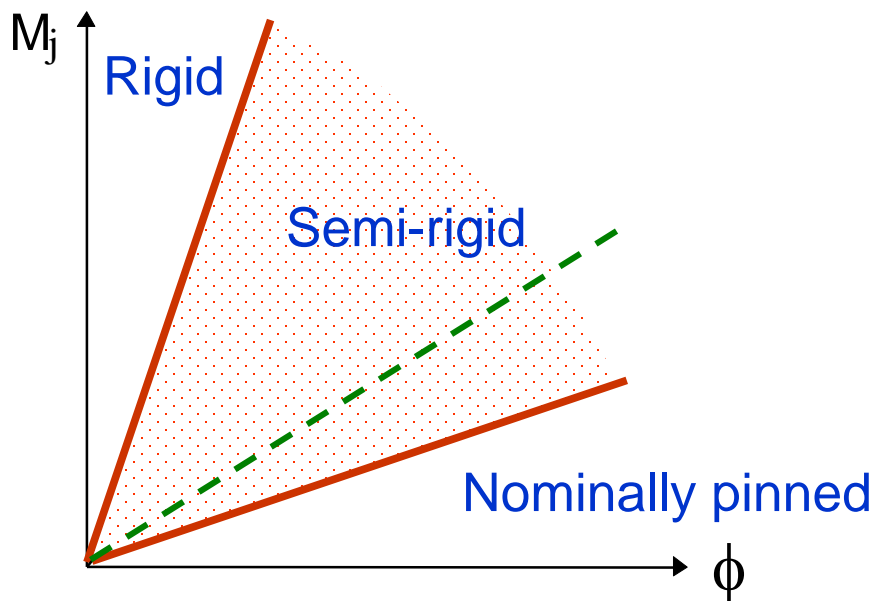


— Limits for classification of joints by stiffness

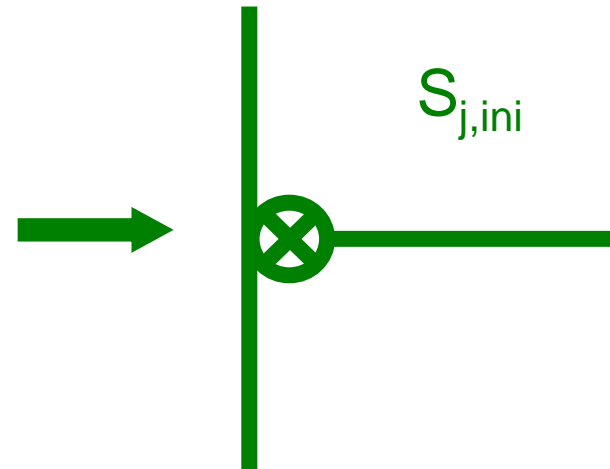
- - - Initial stiffness of the joint

Classification and modelling of joints

“Semi-rigid” joints :



- Limits for classification of joints by stiffness
- - - Initial stiffness of the joint



Classification and modelling of joints

As an alternative to a semi-continuous modelling (semi-rigid joints), is it safe to model the joints as nominally pinned whilst they are actually semi-rigid?

Semi-rigid

$$S_{j,ini} > 0,5EI_b/L_b$$

Partial strength

$$M_{j,Rd} > 0,25 M_{full-strength}$$

??

Nominally pinned

$$S_{j,ini} = 0$$

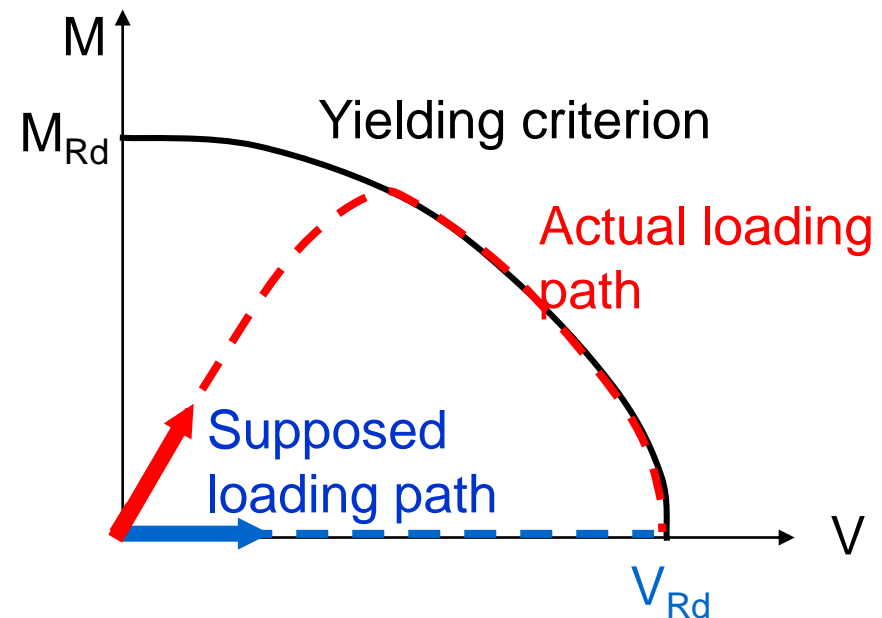
Nominally pinned

$$M_{j,Rd} = 0$$

Classification and modelling of joints

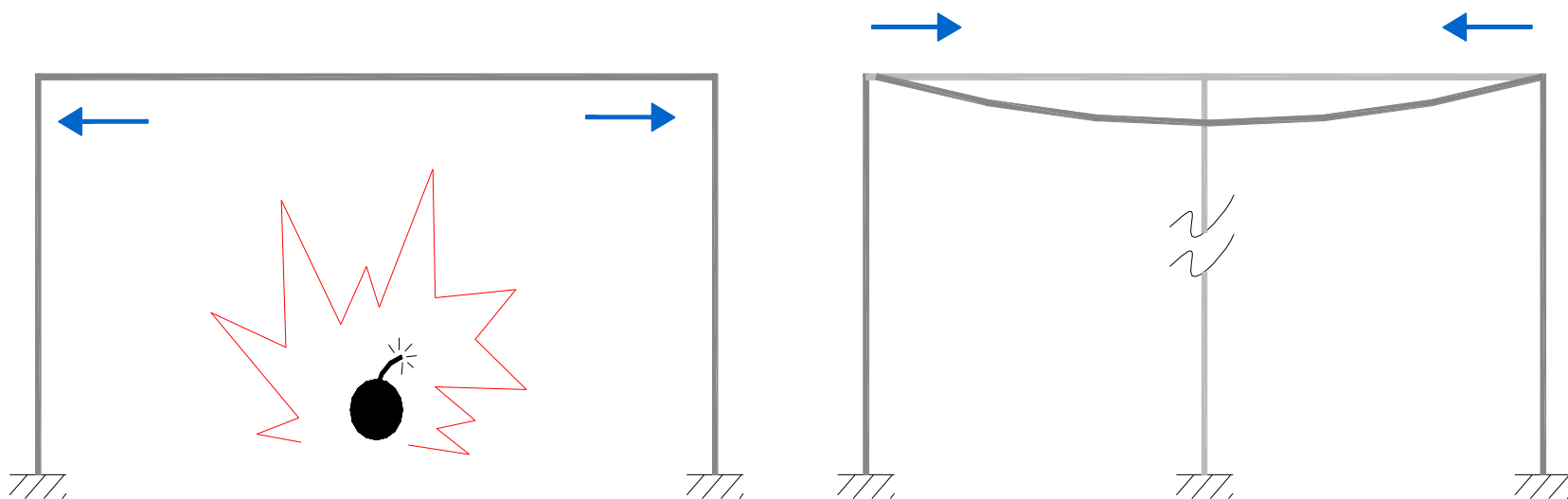
Yes, ...under the reservation the joint has:

- a sufficient rotation capacity
= capacity to “rotate”
- a sufficient ductility
= capacity to follow the actual loading path in a ductile way



Supplementary design requirement

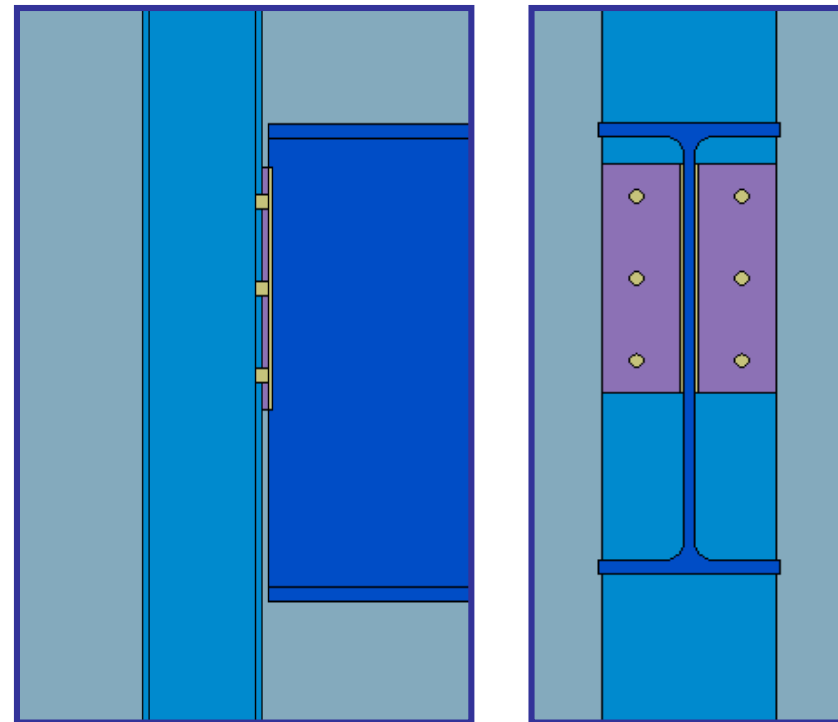
Sufficient resistance to «catenary effects» so as to provide required structural robustness



Example: Partial depth end-plate

Components

- Bolts in shear
- End-plate in bearing
- End-plate in shear (gross section)
- End-plate in shear (net section)
- End-plate in shear block
- End-plate in bending
- Beam web in shear
- Welds in shear
- Column flange in bearing



Partial depth end-plate

Strength requirement

- Use of “component method” for the assessment of V_{Rd}

Assessment of the strength of all the constitutive components of the joint

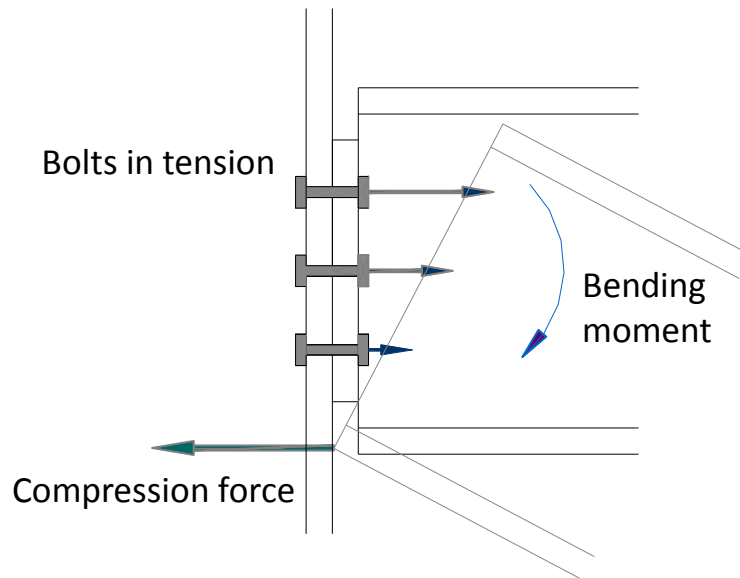


+

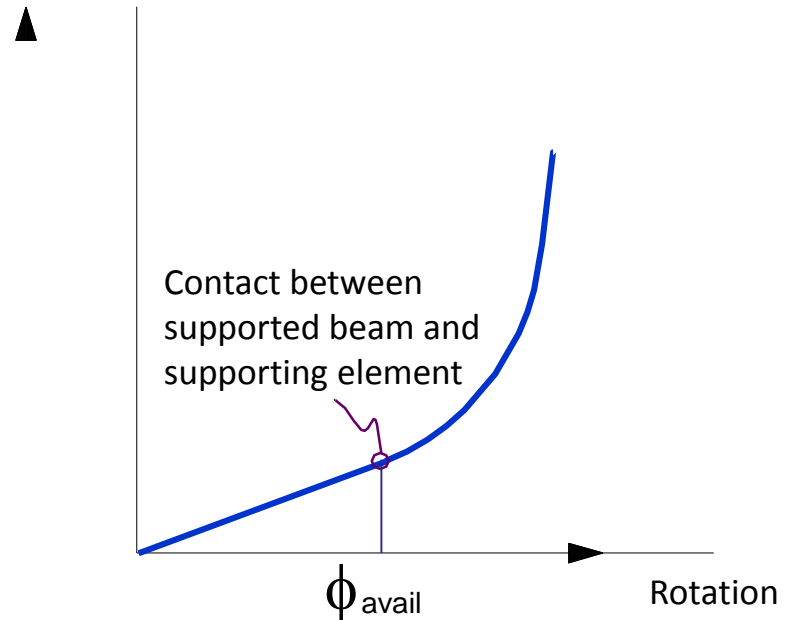
“Assembly” of these components

Partial depth end-plate

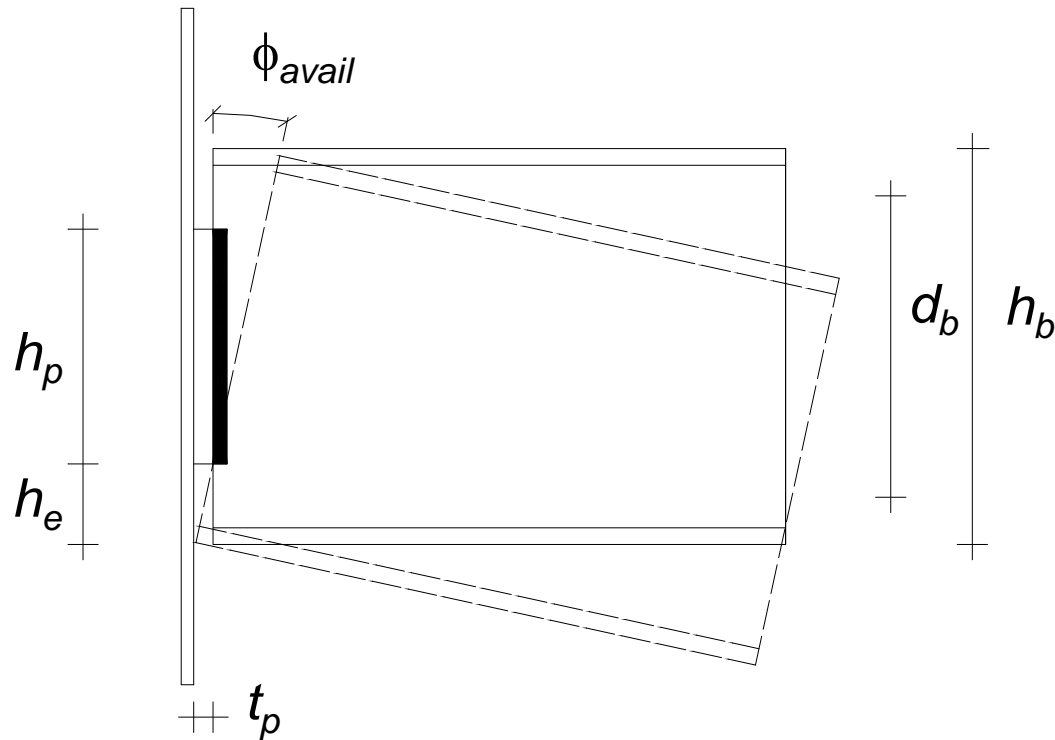
Rotation capacity requirement



Bending moment



Partial depth end-plate



$$h_p < d_b$$
$$\phi_{avail} = \frac{t_p}{h_e}$$

Partial depth end-plate

Ductility requirement

- Prevent premature fracture of the bolts
- Prevent premature fracture of the welds

under unavoidable bending moment in the joint

Partial depth end-plate

Ductility requirements

- Prevent premature collapse of the bolts

$$\frac{d}{t_p} \geq 2,8 \sqrt{\frac{f_{yp}}{f_{ub}}} \quad \text{for the end-plate}$$

$$\frac{d}{t_p} \geq 2,8 \sqrt{\frac{f_{ycf}}{f_{ub}}} \quad \text{for the supporting column}$$

d and f_{ub} : diameter and tensile strength of bolts



Yielding of end-plate prior to tensile fracture of bolts

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Joint
Research
Centre

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- Simple joints
- **Design tools**

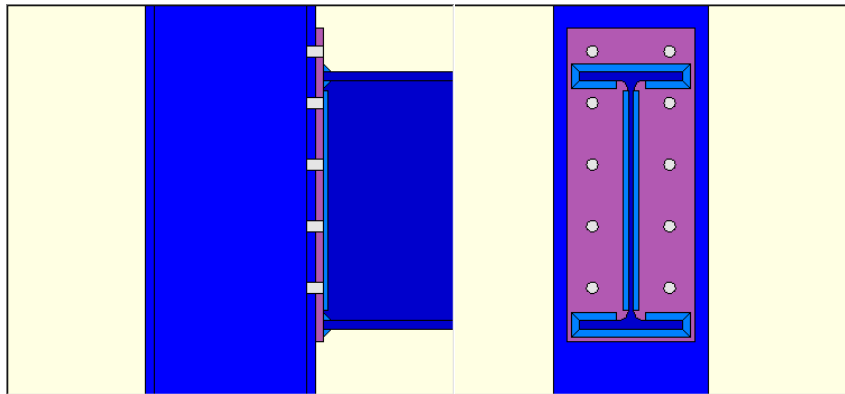
Practical design tools

- Tables of standardized joints



- Dedicated software

Worked Example



Configuration

- Beam IPE 500
- Column HEA 340
- End plate connection

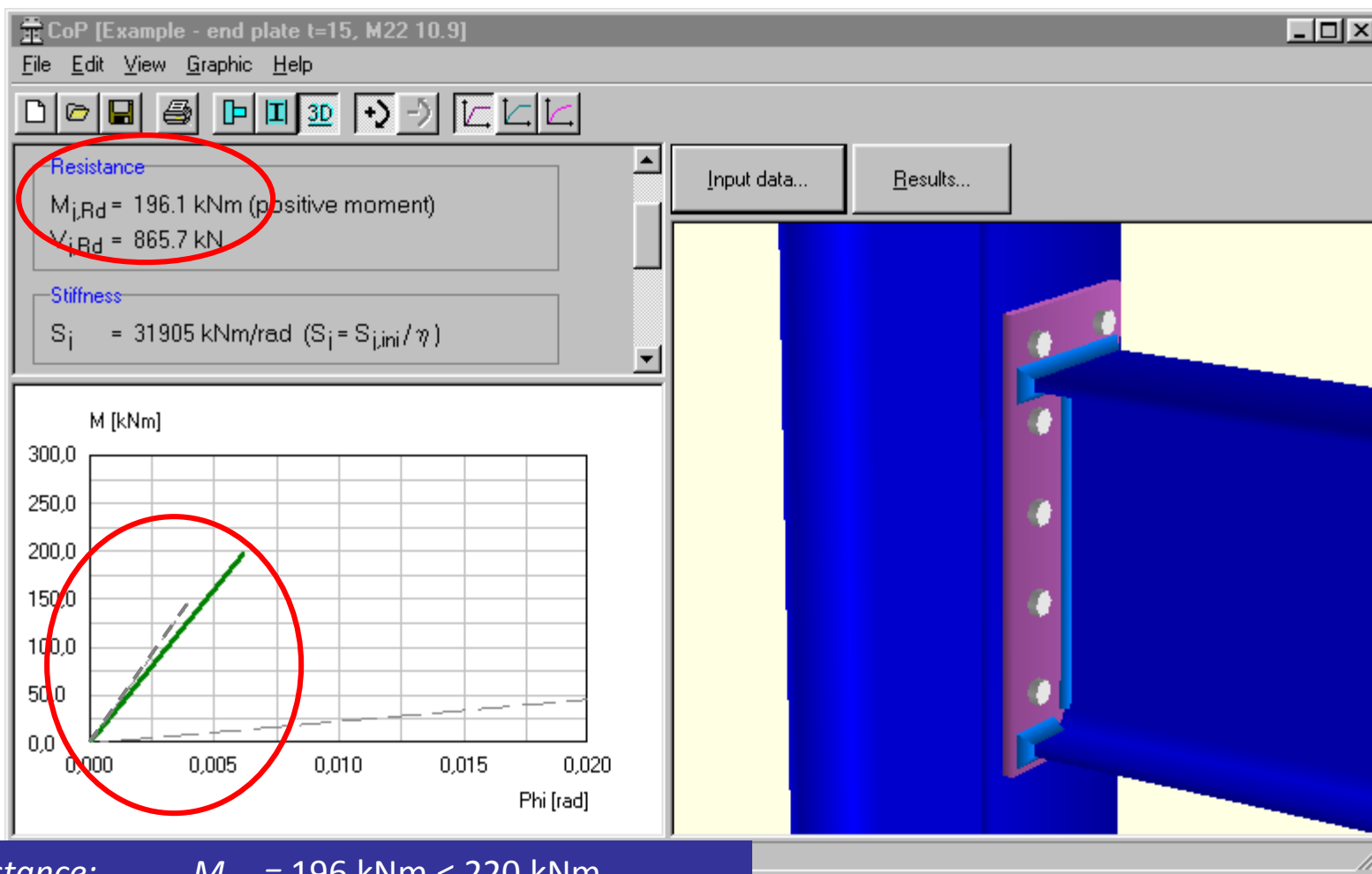
Design assumption

- Rigid joint

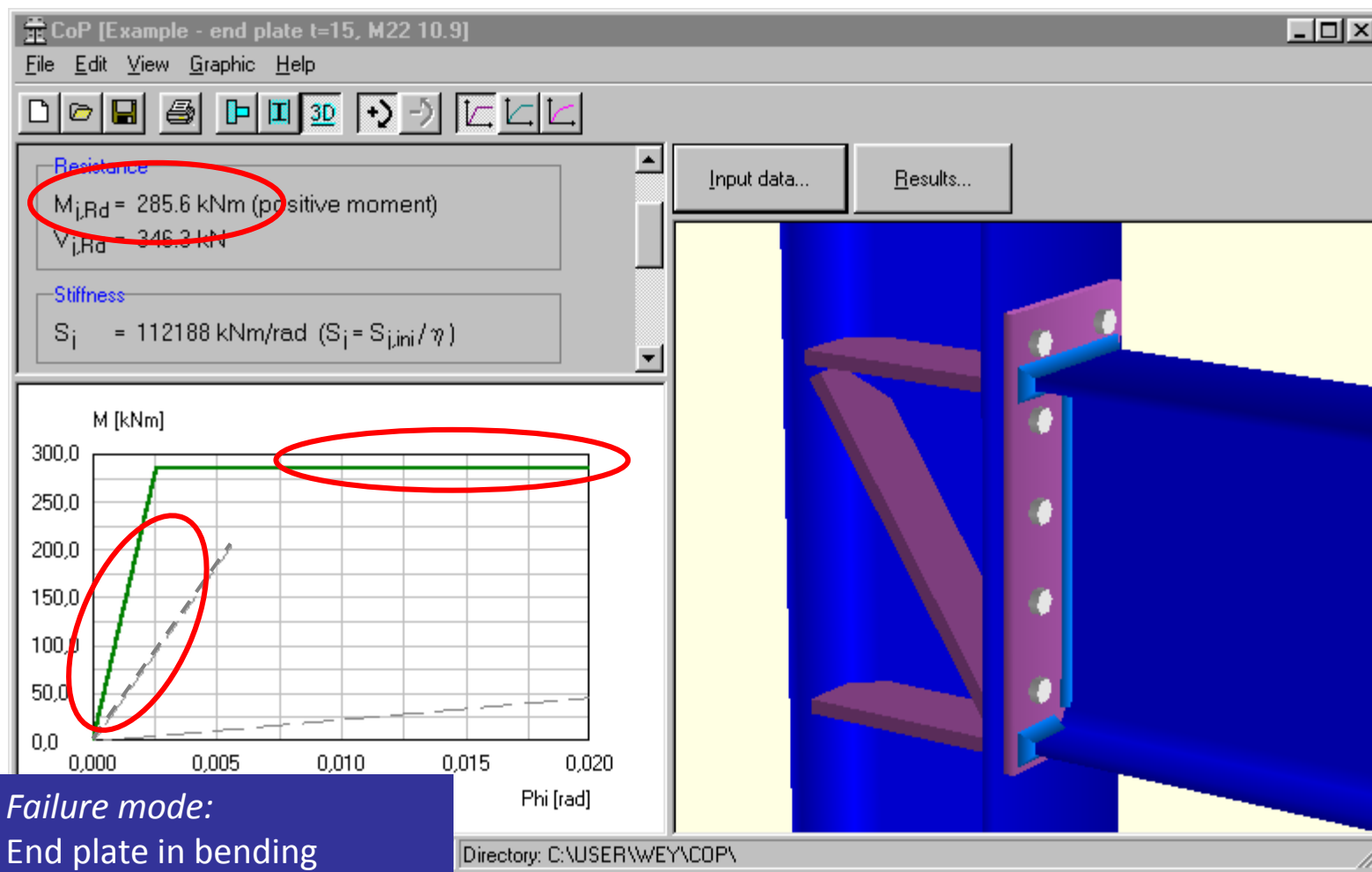
Frame analysis

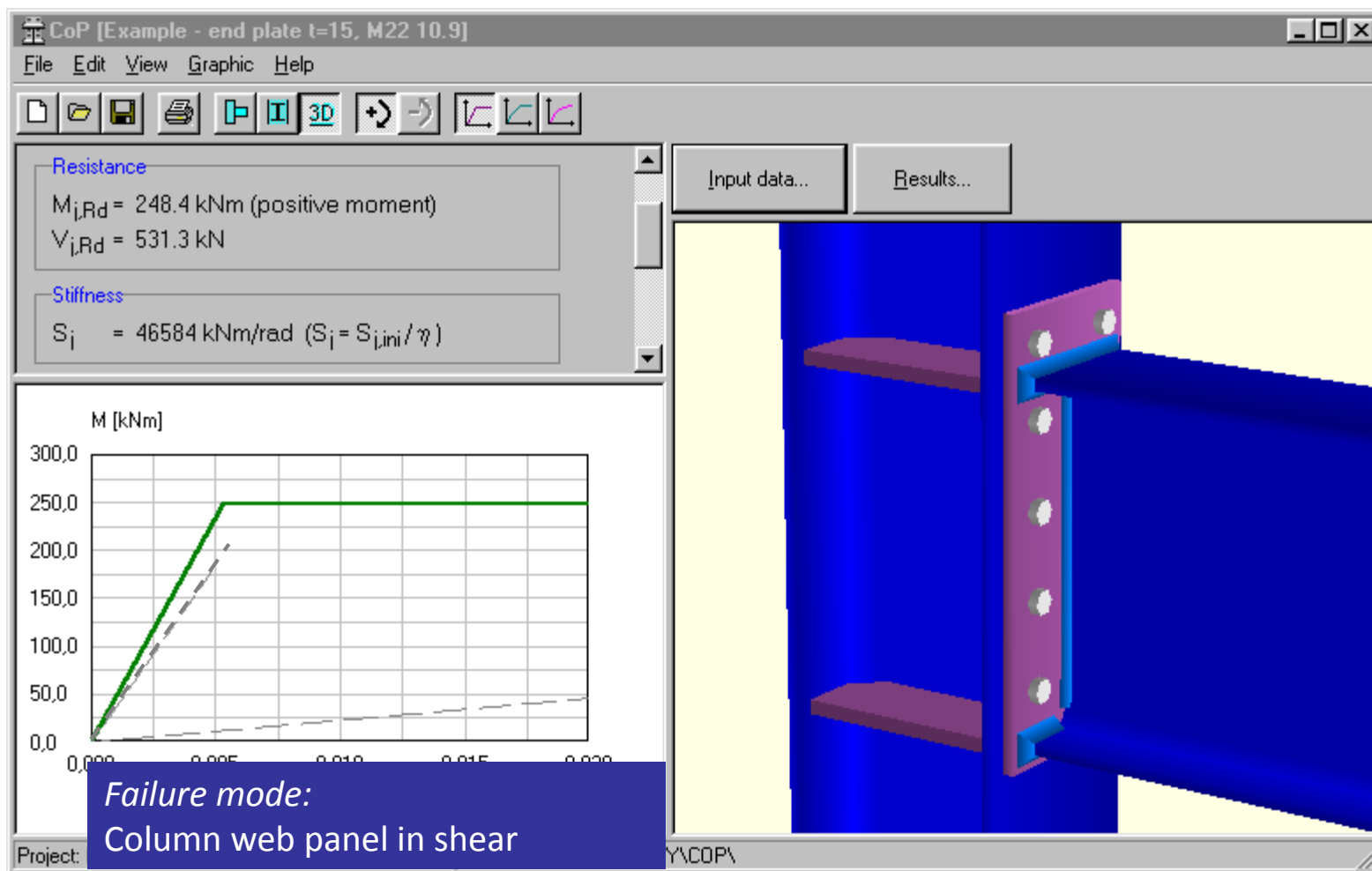
- $M_{Ed} = 220 \text{ kNm}$

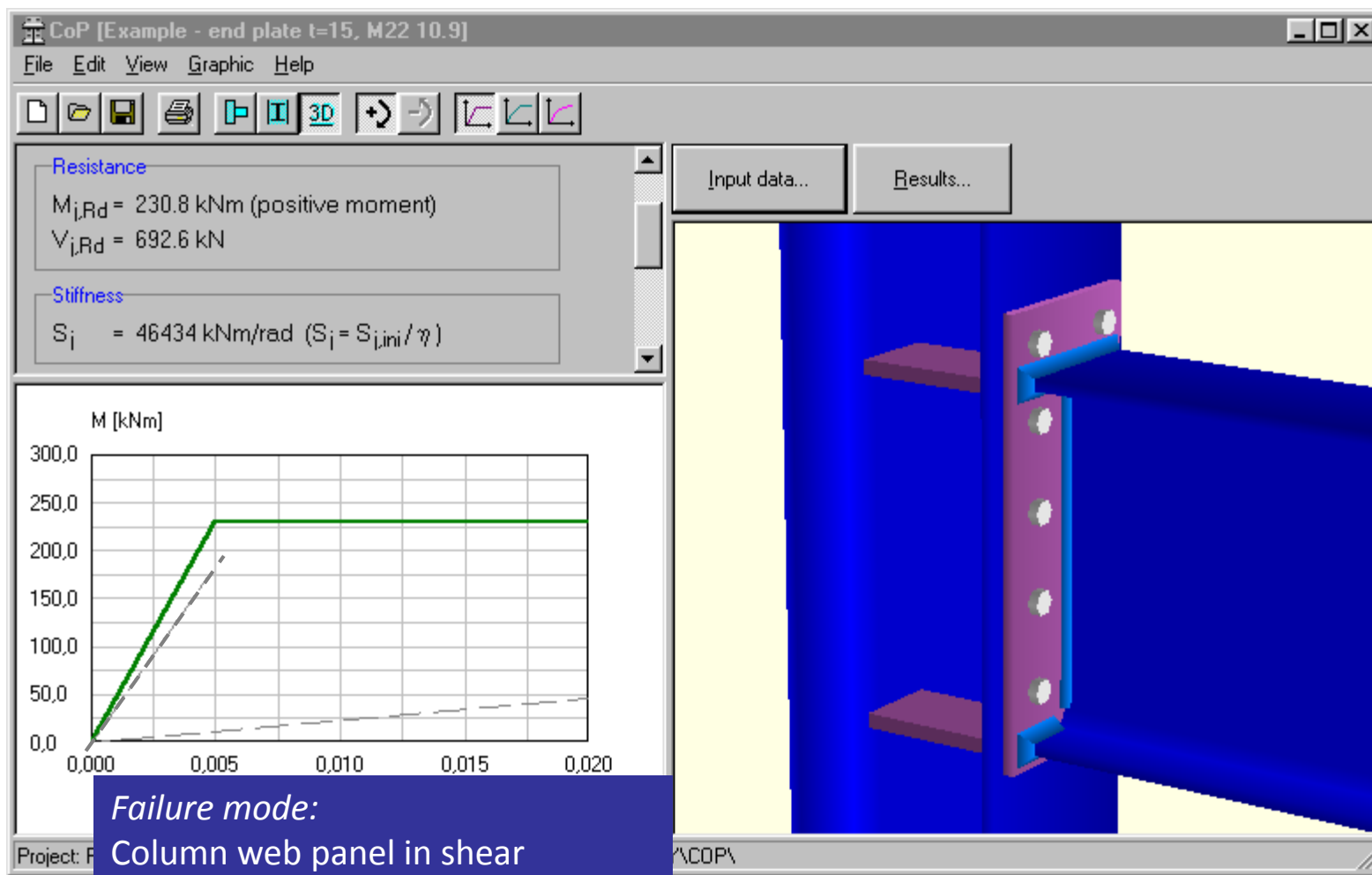
CoP software used for this example: <http://cop.fw-ing.com>

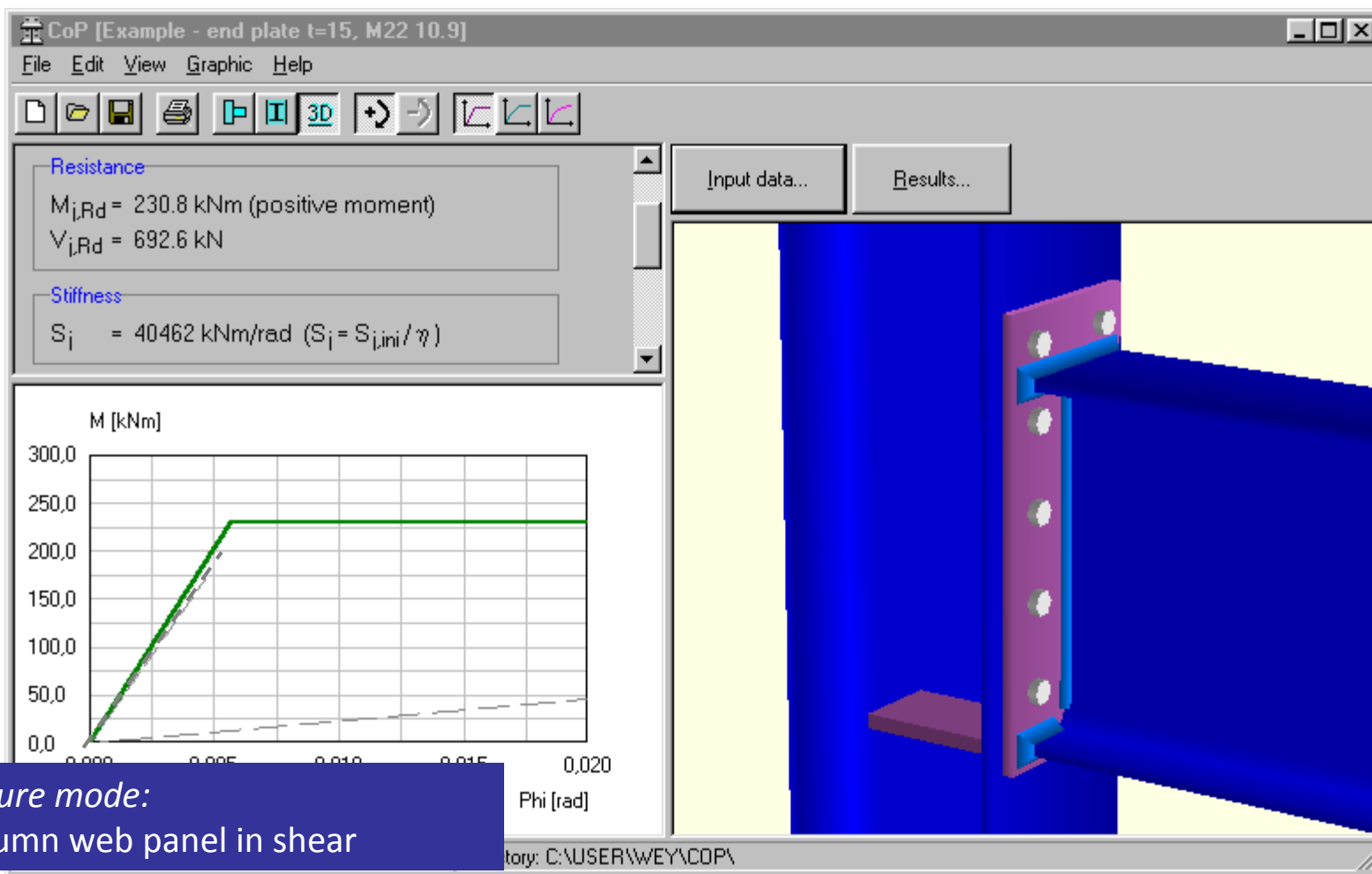


Design resistance: $M_{Rd} = 196 \text{ kNm} < 220 \text{ kNm}$
Classification: Semi-rigid
Failure mode: Column web in compression









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Design of Structural Steel Joints

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